

SEDAR

Southeast Data, Assessment, and Review

SEDAR 87

Gulf White Shrimp

SECTION III: Assessment Process Report

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June 5, 2025 First letter of all species, regions, and size classes capitalized for consistency.



SEDAR87 Gulf White Shrimp Benchmark Assessment

Gulf Branch Sustainable Fisheries Division NOAA Fisheries - Southeast Fisheries Science Center

June 2025

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1. Assessment Process Proceedings

On January 20, 2025, President Trump issued Executive Order 14172 to rename the Gulf of Mexico as the Gulf of America. Any reference to Gulf of America White Shrimp in SEDAR reports and other documents refers to the same species and fishery listed in 50 CFR part 622, Subpart C (Shrimp Fishery of the Gulf of Mexico). As of the publication of this report, all efforts were made to use "Gulf of America" per Executive Order 14172. However, previous NOAA reports (cited herein) may have referred to this water body as the "Gulf of Mexico".

1.1 Introduction

1.1.1 Workshop Time and Place

The SEDAR 87 Assessment Process (AP) for Gulf White Shrimp was conducted via a series of webinars held between October 2024 and February 2025.

1.1.2 Terms of Reference

- 1. Review any changes in data or analyses following the Data Workshop. Summarize data as used in each assessment model. Provide justification for any deviations from Data Workshop recommendations.
- 2. Develop a management advice framework. Consider data availability (e.g., landings and catch-per-unit-effort [CPUE]) and management needs (e.g., harvest controls, stock status), and particular needs of the fishery and the biology of the resource.
- 3. Examine the impacts of social science factors on biological reference points as informed by stakeholders through industry input.
- 4. Recommend biological reference points for use in management.
 - Consider how reference points could be affected by management, ecosystem, climate, species interactions, habitat considerations, social or economic drivers, and/or episodic events.
- 5. Provide estimates of stock population parameters, including: Fishing mortality, biomass, selectivity, and/or other parameters as necessary to describe the population.
- 6. Characterize uncertainty in the assessment and estimated values.

- o Consider uncertainty in input data, modeling approach, and model configuration.
- o Provide appropriate measures of model performance, reliability, and 'goodness of fit'.
- Provide measures of uncertainty for estimated parameters and derived quantities such as biological reference points and stock status if feasible.
- 7. Provide recommendations for future research and data collection. Emphasize items that will improve future assessment capabilities and reliability. Consider data, monitoring, and assessment needs.
- 8. Complete an Assessment Workshop Report in accordance with project schedule deadlines.

1.1.3 List of Participants

Assessment Process Participants	
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1.1.4 List of Assessment Process Working Papers and Reference Documents

Document #	Title	Authors	Date Submitted			
	Documents Prepared for the Assessment Process					
SEDAR87-AP-01	Development of estuarine environmental indices for SEDAR 87 Gulf of Mexico White, Pink, and brown shrimp stock assessment	Brendan Turley, Lisa Ailloud, and Molly Stevens	25 July 2024			
SEDAR87-AP-02	Price Indices for Shrimp Imports and Gulf of Mexico Shrimp Landings by Size and Season	Christopher Liese	18 December 2024			
SEDAR87-AP-03	Developing a fishery-independent index of relative abundance for Gulf of Mexico Brown Shrimp using VAST	Lisa Ailloud, Molly Stevens, Brendan Turley, Adam Pollack, and David Hanisko	31 January 2025			

SEDAR87-AP-04	Developing a fishery-independent index of relative abundance for Gulf of Mexico Pink Shrimp using VAST	Lisa Ailloud, Molly Stevens, Brendan Turley, Adam Pollack, and David Hanisko	31 January 2025	
SEDAR87-AP-05	Developing a fishery-independent index of relative abundance for Gulf of Mexico White Shrimp using VAST	Lisa Ailloud, Molly Stevens, Brendan Turley, Adam Pollack, and David Hanisko	31 January 2025	
	Reference Documen	its		
SEDAR87-RD12	JABBA: Just Another Bayesian Biomass Assessment	Henning Winker, Fel Kapur	ipe Carvalho, Maia	
SEDAR87-RD13	Empirical dynamic modeling for sustainable benchmarks of short-lived species	Cheng-Han Tsai, Ste Michelle D. Masi, an		
SEDAR87-RD14	Recent developments in empirical dynamic modelling	Stephan B. Munch, T George Sugihara	Sanya L. Rogers,	
SEDAR87-RD15	Comparing estimates of abundance trends and distribution shifts using single- and multispecies models of fishes and biogenic habitat	James T. Thorson and Barnett	d Lewis A. K.	

2. Data Review and Update

The following list summarizes the data inputs (and units) used in the assessment modeling process along with their corresponding available temporal scale based upon recommendations from the Data Workshop process. Two assessment modeling platforms were considered: a Bayesian surplus production model, JABBA (Just Another Bayesian Biomass Assessment), and an Empirical Dynamic Modeling (EDM) platform (see *Section 3*). Data for JABBA were on an annual time scale and included commercial landings (in million pounds of tails) and an index of abundance built with LDWF survey data using Vector Auto-Regressive Spatio-Temporal (VAST) modeling (Ailloud et al. 2025). EDM explored all the datasets listed below using various levels of stratification. JABBA allowed for different start years of data inputs, while EDM was limited by the start year of the survey data. For EDM, data were stratified by fishing area [A (*Figure 1*): 1-10, 11-17, 18-21], size [S: >67 (Small), 67-31 (Medium), <=30 (Large)

tails per pound], and quadrimester of the year [Q: January-April (Winter), May-August (Summer), September-December (Fall)] where possible, and are indicated as such in the data list. Stratifications were defined based on existing definitions of the ecological distribution of shrimp and the shrimping industry.

- 1. Commercial landings (10 million pounds of tails): 1960-2022 [A, S, Q]
- 2. LDWF survey data (number of shrimp per 10min trawl): 1980-2022 [A, S, Q]
- 3. Ex-Vessel price indices (2022 dollars): 1960-2023 [S, Q]
- 4. Imports (product volume in 100 million pounds): 1972-2022 [Q]
- 5. Salinity (practical salinity unit): 1980-2022 [A]
- 6. Bottom temperature (degrees Celsius): 1980-2022 [A]

White Shrimp are distributed primarily in the western Gulf (*Figure 1* : 11-21). Possible data stratifications for White Shrimp EDM were defined as:

- A) Aggregated: ANNUAL; SIZE BINS AGG; AREA AGG (11:21)
- B) [Stratum N/A because single area]
- C) Size: ANNUAL; SIZE BINS (>67, 67-31, <=30); AREA AGG (11:21)
- D) [Stratum N/A because single area]
- E) Season: SEASONAL (SUMMER, FALL, WINTER); SIZE BINS AGG; AREA AGG (11:21)
- F) [Stratum N/A because single area]
- G) Size_Season: SEASONAL (SUMMER, FALL, WINTER); SIZE BINS (>67, 67-31, <=30); AREA AGG (11:21)
- H) [Stratum N/A because single area]

For White Shrimp, additional strata were included that aggregated the Medium and Large size classes into a Marge size class containing all shrimp greater than <=67 tails per pound.

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Cml) Size: ANNUAL; SIZE BINS (>67, <=67); AREA AGG (11:21)
Gml) Size_Season: SEASONAL (SUMMER, FALL, WINTER); SIZE BINS (>67, <=67);
AREA AGG (11:21)
```

2.1 Stock Structure and Management Unit

The SEDAR 87 Gulf White Shrimp Benchmark Assessment stock boundary extends from the United States—Mexico border in the west through the northern Gulf of America waters (hereafter referred to as the Gulf) to the Dry Tortugas and Florida Keys. This includes all waters within the Gulf of Mexico Fishery Management Council (hereafter referred to as the Gulf Council) boundaries and extends to include fishing areas split by the eastern boundary off the Florida Keys (*Figure 1*: Areas 002, 001) in their entirety due to complications with reporting over time (Atkinson et al. 2024). This stock boundary distinction is most important for Pink Shrimp due to its distribution being centered in the eastern Gulf, but it was applied to all Gulf shrimp species.

2.2 Fishery-Independent Survey Data

2.2.1 Louisiana Department of Wildlife and Fisheries Survey

The Louisiana Department of Wildlife and Fisheries (LDWF) survey is a state survey run by Louisiana and is collected monthly. The Indices WG at the Data Workshop deemed these data representative for White Shrimp since 1980 for all size classes (SEDAR87 data workshop report 2023; LDWF 2024). The monthly indices were averaged to form seasonal series of abundance for each size class (Figure 2), where these data were combined to form annual abundance estimates by size class (Figure 3). Raw annual indices for White Shrimp are shown by size class in Table 1. This survey operates inshore and has a much higher CPUE for Small shrimp compared to Large shrimp. A log-transformed CPUE is shown in Figure 4 to better visualize the increase in abundance for all White Shrimp size classes in the mid-2000s.

2.2.2 Vector Autoregressive Spatio-Temporal (VAST) Index

VAST is a spatio-temporal modeling platform that can be used for standardizing indices of relative abundance. Data from one or more surveys are combined to predict population density based on both habitat covariates (that impact abundance) and spatial and spatio-temporal random effects, while controlling for catchability covariates (that impact sampling efficacy). A VAST index was developed for White Shrimp based on data from LDWF survey for input into JABBA. Details of the VAST index are documented in Ailloud et al. (2025).

2.3 Fishery-Dependent Data

2.3.1 Commercial Landings

Commercial landings of White Shrimp were constructed using data from the Gulf Shrimp System (GSS) and state trip ticket programs. Species-specific Gulf shrimp landings have been collected since the late 1950s, and their complex history within the federal and state databases, including justifications for the relative coefficients of variance (CVs) through time, is documented in great detail in Atkinson et al. (2024). Landings were converted to tail weight for input to the assessment model.

Shrimp landings (*Table 2*) have been sold and recorded in eight market categories which were aggregated into three general size classes (*Figure 5*): Large, Medium, and Small. These are shown broken out seasonally (*Figure 6*) and aggregated annually (*Figure 7*). Changing economic conditions in the mid-2000's are described in the following section and Griffith et al. (2023) and resulted in the targeting of larger shrimp by the domestic fleet. For White Shrimp, Large landings became dominant primarily in the Summer season (*Figure 6*) while population sizes increased (*Figure 4*). White Shrimp landings peaked in 2006 with landings totaling 85.12 million pounds of tails. The seasonal distribution of White Shrimp landings through time is shown in *Figure 8*.

2.4 Economics and Social Sciences

2.4.1 Imports and Ex-vessel Price Indices

Imported shrimp have exceeded the volume of domestically caught shrimp since the 1980's (Lowther 2023; Atkinson et al. 2024). In the mid-2000s, the volume of imported shrimp increased dramatically, particularly for Large shrimp which has a higher market value, causing domestic ex-vessel prices to plummet (*Figure 9*). Time series of imports and ex-vessel prices were both considered during EDM development (Liese 2024).

2.4.2 Industry Impacts

The globalization of the shrimp market with a focus on cheap aquaculture has resulted in dire economic operating conditions for the domestic fleet (Griffith et al. 2023). Increasing fuel costs and plummeting ex-vessel prices have created a situation in which most vessels struggle to remain profitable. Further, many vessels have exited the fleet, and those that remain may oscillate between narrowing profit margins and losses (*SEDAR87 data workshop report* 2023 pp. 84–94). With fewer vessels operating, the shrimping effort and associated landings have decreased overall, and the shrimp population size has increased.

Industry impacts were documented during a stakeholder listening session at the Data Workshop, with the intention of holding additional listening sessions throughout coastal Gulf shrimping communities. During this session, resource users stated that the troubles of the Shrimp Fishery cannot be improved by domestic fishery management solutions. The bulk of the problems are globally influenced, and this fishery was recommended to the National Seafood Strategy to address these problems if possible, informed by additional information gathered through the newly formed *Shrimp Futures Project*.

2.5 Environmental Indices

Annual shrimp recruitment has been tied to environmental drivers in the past (Browder et al. 2002; Zink et al. 2018; Schlenker et al. 2023). Within an assessment modeling framework, it is important to include drivers of abundance at the most meaningful spatio-temporal scale. At the SEDAR 87 Data Workshop, the Environment and Industry Working Group recommended that salinity and temperature in the nursery grounds during the months that the shrimp were in their respective nursery grounds were likely the primary environmental drivers for shrimp abundance. These two variables were hypothesized to best explain the magnitude of recruits into the population each year. The methodology used to derive White Shrimp temperature and salinity indices was outlined in Turley et al. (2023). These indices were considered in the construction of the VAST index and development of EDM.

White Shrimp is in its inshore nursery grounds August through October every year throughout its coastal range. It was hypothesized that the environment would affect the overall population abundance more directly through its impact on the young of the year in this volatile habitat. While there may be some impacts of seasonal differences in rainfall and temperature fluctuations affecting local abundance, the trends of data from both TX (north of Laguna Madre) and LA appeared to follow strikingly similar trends, indicating consistency throughout the range

(*Figure 10*). Since EDM benefits greatly from a longer time series, it was decided to include LA-only data which go back to 1980 (*Figure 11*).

2.5.1 Temperature

Temperature in the western Gulf follows trends of state temperature averages from TX (north of Laguna Madre) to LA, with LA experiencing more extreme lows in some years. The standardized temperature index represents the nursery conditions well, which was similar on average, throughout these variable estuarine habitats. The combined index was very similar to the LA only data, which were used to include data back to 1980 as opposed to 1987.

2.5.2 Salinity

While salinity in TX was much higher compared to salinity in LA, both states generally experienced co-occurring peaks and troughs, resulting in a standardized index that tracks changes in salinity well. The combined and LA-only salinity index track similar trends, but the LA-only index was included in the EDM model to obtain additional time steps.

3. Stock Assessment Model Configurations and Methods

Two modeling frameworks were evaluated for the Gulf White Shrimp SEDAR 87 Benchmark Assessment: Just Another Bayesian Biomass Assessment (JABBA) Model and Empirical Dynamic Modelling (EDM). These are described below.

3.1 Just Another Bayesian Biomass Assessment (JABBA) Model

JABBA is a Bayesian state-space surplus production model (SPM) framework that is documented in Winker et al. (2018) and is available as an R package on *GitHub*. SPMs pool the overall effects of recruitment, somatic growth, natural mortality, and associated density-dependent processes into a single production function dealing with undifferentiated biomass (Haddon 2021). The state-space formulation allows for the estimation of observation and process error, and the Bayesian formulation allows the user to define prior distributions for each parameter in the model to represent the initial beliefs about the parameter before observing any data. Primary data inputs into JABBA are indices of abundance proportional to the exploitable part of the stock biomass and a time series of fishery removals. The time series of removals can begin prior to the indices of abundance, and contrast in the data is required to appropriately map the stock dynamics.

The generalized surplus production function (Pella and Tomlinson 1969) used by JABBA is defined as

$$SPM_t = \frac{r}{m-1} \left(1 - \frac{B_t^{m-1}}{K} \right)$$

where r is the intrinsic rate of population increase at time t, K is the carrying capacity, B is the stock biomass at time t, and m is the shape parameter that determines at which B/K ratio maximum surplus production is attained. The Pella-Tomlinson function above is a generalized production function with Schaefer (m = 2) and Fox (m = 1) as special cases. The Schaefer may

be the most well-known, with a symmetrical production curve and Maximum Sustainable Yield (MSY) attained at half the carrying capacity, B = K/2.

JABBA has several features including the ability to a) fit multiple CPUE time series and associated standard errors, b) estimate or fix the process variance, c) estimate additional observation variance on individual or grouped CPUE series, and d) specify either a Fox, Schaefer or Pella-Tomlinson production function. A full JABBA model description, including formulation and state-space implementation, prior specification options, and diagnostic tools is available in Winker et al. (2018).

3.1.1 Estimated Parameters

JABBA model parameters are defined in greater detail below.

K: Carrying capacity (million lb tail weight)

m: Shape parameter of the Pella-Tomlinson that determines at which B/K ratio maximum surplus production is attained. If m=2, the model reduces to the Schaefer form, with the surplus production (SP) attaining MSY at exactly K/2. If 0 < m < 2, SP attains MSY at biomass levels smaller than K/2; the converse applies for values of m greater than 2.

 ψ : Ratio of the spawning biomass in the first year to K.

q: Catchability coefficient.

r: Intrinsic rate of population increase.

 σ^2 : Process variance.

 τ^2 : Additional observation variance for the survey index.

3.1.2 Model Configurations and Prior Assumptions

The final VAST index built on LDWF survey data presented in Ailloud et al. (2025) was used as input to JABBA alongside an annual time series of commercial catches spanning 1960-2022 (Section 2.3.1). The following CVs were recommended by the WG and input into JABBA to reflect uncertainty in landings based on changes in the sampling programs through time. 1960-1983: CV = 0.2, 1984-2015: CV = 0.1, 2016-2022: CV = 0.05. The time series and associated confidence intervals are shown in Figure 12 and 13. Model configurations and prior distributions were defined as follows:

Carrying capacity (K): uninformative prior. Lognormal distribution specified using the "range" option in JABBA with lower and upper values ranging from maximum catch to 10x maximum catch (*Figure 14*)

Production function: Pella-Tomlinson (MSY at $B_{MSY}/K = 0.4$; CV = 0.3) where B_{MSY} is the biomass at MSY (Figure 15)

Process error variance (σ^2): Default $1/\gamma(4,0.01)$ (Figure 16). This matches the level of process error where state-space SPMs are most likely to adequately perform.

Observation error variance (if estimated) (τ^2): Default ~ $1/\gamma(0.001,0.001)$ (Figure 17)

r prior: informative priors were developed based on the Medium (0.2-0.8) and High (0.6-1.5) resilience categories in FishBase (Froese et al. 2019). Given that FishBase does not include any crustaceans and that shrimp are likely on the higher range of r compared to most fishes, an additional Very High (1.2-3) prior was tested (*Figure 18*)

Initial biomass depletion ratio (ψ): two alternative priors were tested to reflect Low initial depletion lognormal(0.9,0.25) and and High initial depletion lognormal(0.25,0.5) at the beginning of the catch time series ($\psi = B_{1960} / K$) (Figure 19)

A factorial design was used to test a suite of models with alternative prior assumptions about r, ψ and τ^2 . The naming convention for candidate model is as follows:

SpeciesCode_ModelRun_ProductionCurve_rPrior (H:High,M:Medium,V:Very High)_PsiPrior(High:0.2,Low:0.9)_ObservationError(T=TRUE,F=False)_StartYearCatches For example,

WSH_4_P_rM_psil0.9_sigT_60: White Shrimp (WSH_) run number 4 (_4) using a Pella-Tomlinson surplus production curve (_P), Medium r prior (_rM), low initial depletion (_psil0.9) with additional observation error being estimated (_sigF) and a catch time series starting in 1960 (60)

3.1.3 Model Diagnostics

Candidate models were assessed based on the following four criteria (Carvalho et al. 2021):

3.1.3.1 Model Convergence

The Geweke convergence diagnostic (CONV_gw) compares the mean of the first and last part of Markov chain to see if they are significantly different. Z scores near 0 (between -1.96 and 1.96) are considered acceptable (Geweke 1992).

Heidelberger and Welch stationarity diagnostic (CONV_hs) shows the iteration number from which the chain is considered to have converged and an associated p value, where the null hypothesis is that the sampled values come from a stationary distribution (Heidelberger and Welch 1983). 'Failure' of the stationarity test indicates that a longer MCMC run is needed. The Heidelberger and Welch half-width test (CONV_hw) checks whether the Markov chain sample size is adequate to estimate the mean values accurately (Heidelberger and Welch 1983).

3.1.3.2 Model Fit

Catch-per-unit-effort (CPUE) residuals runs test: CPUE indices pass the runs test (CPUE_rt_rand) if there is no evidence of a non-random residual pattern (p > 0.05). Any year where the residuals are larger than the threshold limit [3 standard deviations (sd) away from the mean (Anhøj and Olesen 2014)] fail the outlier test (CPUE_rt_outl).

3.1.3.3 Model Consistency

Retrospective analysis: This test checks for systematic bias in the stock status estimates. The procedure involves sequentially removing all data from the most recent period (i.e. peeling), refitting the model, and then comparing terminal year estimates of stock status [e.g. spawning stock biomass (SSB), fishing mortality (F)] to the full model. A guiding practice proposed by Hurtado-Ferro et al. (2015), suggests values of Mohn's rho (RETRO_) that fall outside a set range (-0.22 to 0.30) for shorter-lived species indicates an undesirable retrospective pattern. In addition, the direction of the retrospective bias has implications for characterizing risk associated with management advice.

Process error: The annual process error deviations should exhibit a stochastic pattern with a constant average centered around the zero (ProcB_mu) and 95% credibility intervals covering the zero value (ProcB_CI).

3.1.3.4 Prediction Skill

Hindcast cross-validation (Kell et al. 2016, 2021): this test is to check that the model has prediction skill of future states under alternative management scenarios. The procedure involves sequentially removing CPUE data from the most recent period, refitting the model with the remaining data, and then comparing known CPUE values (observations) to model estimates.

Mean Absolute Scaled Error (HX_MASE): The MASE score scales the mean absolute error of the prediction residuals to the mean absolute error of a naive in-sample prediction (i.e. equal to the last observed value). A score of 0.5 indicates that the model forecasts of CPUE values are twice as accurate as a naive in-sample prediction, indicating that the model has prediction skill. A score higher than 1 indicated that the model forecasts are no better than a random walk. If MASE < 1, the model has some level of prediction skill and passes the test.

3.1.4 Goodness of Fit

Deviance Information Criteria (DIC) was used for model selection purposes, where a lower value generally indicates a better model fit. Root-Mean-Squared-Error (RMSE) was used to quantitatively evaluate the randomness of model residuals. These criteria were used to determine the best model of those that passed the model diagnostic tests described in the previous section.

3.2 Empirical Dynamic Modelling (EDM)

Empirical Dynamic Modelling (EDM) uses lags of time series data to reconstruct the state-space of a system (Sugihara 1994; Sugihara et al. 2012; Munch et al. 2017, 2022). This form of modeling is particularly useful for short-lived species with chaotic population dynamics where drivers are often not observed directly, yet the information is embedded within the time series of abundance. Lags of abundance indices are used to reconstruct the full dynamics of the system without needing data on variables impacting abundance or specifying model form. Gaussian-Process EDM (GP-EDM) version 0.0.0.9010 on *GitHub* was used to fit the LDWF survey data aggregated at levels defined in *Section 2*. We also tested the inclusion of economic and environmental variables as covariates since they are hypothesized drivers of shrimp abundance where measurements do exist.

3.2.1 Model Configurations

3.2.1.1 Formulation with Fishery Removals

Gaussian Process regression was used to approximate the White Shrimp population delayembedding map f

$$P[y_t \mid f, (X_{t-m} - q * C_{t-m}), z, V_e] \sim Normal(f(X_{t-m} - q * C_{t-m}, z), V_e)$$

where the probability of observing abundance y at time t is dependent on the function approximation f, vector of abundance indices X with m lags $(X_{t-m} = x_{t-1}, ..., x_{t-m})$, optional covariates z, and process variance V_e . The delay embedding map defined above was expanded to include removals (C, catch or landings) scaled by a catchability parameter q which can be fit within or among populations. Here, catchability is a scalar used to translate units of landings into survey units. Covariates (z) can be included as direct drivers of abundance where measurements exist. Fitting to 'escapement', the composite variable $X_{t-m} - q * C_{t-m}$ is the number of individuals remaining after harvesting. GP-EDM with a single lag m=1 can be thought of as a nonparametric production model (Thorson et al. 2014). f is dependent on the inverse length scales $\Phi = \phi_1, \ldots, \phi_{i=m+z}$ and pointwise prior variance τ and follows a Gaussian Process prior with mean zero and covariance function Σ , which assumes no relationship on the shape function.

$$P[f \mid \Phi, \tau] \sim GP(0, \Sigma)$$

The covariance function Σ is defined for abundance γ

$$\Sigma(y_t, y_s) = \tau * exp[-\Sigma_{i=1}^{m+z} \phi_i (X_{it} - X_{is})^2]$$

at times t and $s \in T$ where T is the time series length (Munch et al. 2022). The inverse length scale parameters ϕ and abundance observations X are provided for each i = m + z where m is the lags of abundance and z is the covariates. This function is scaled by τ , and a prior is applied here that constrains the total variance of the predicted population size (y_{T+1}) to be less than twice the observed variance in y_1, \ldots, y_T . This prior specification for process and observed variances and length scale parameters are represented by

$$P[V_e, \tau, \Phi]$$

The covariance function and inverse length scales jointly control the degree of nonlinearity of the shape function f, where $\phi = 0$ indicates a flat relationship and a large estimate for ϕ indicates a higher degree of nonlinearity. The covariance function Σ can either tighten the relationship around the observed data, favoring a smaller length scale (i.e. a larger inverse length scale parameter) or relax the relationship, facilitating a smoother function with a larger length scale (smaller ϕ). Detailed GP prior specification for EDM variance and length scale parameters can be found in Munch et al. (2017).

An optional feature of GP-EDM is to assign a linear prior on f which can aid in grounding the population to 0 as the harvest rate, U, approaches 1 (i.e. the entire population is harvested). The linear prior option assumes that the mean function for the GP is linear with respect to the first input and fits the model on the residuals of

$$y_t = \beta_0 + \beta_1 [x_{t-1} - q * c_{t-1}] + f(X_{t-m} - q * C_{t-m}, z)$$

where $[x_{t-1} - q * c_{t-1}]$ is first lag of escapement and f is the GP function approximation. If $y_t = log(x_{t+1}/x_t)$ and is backtransformed, this is equivalent to a Ricker model excluding f (Ricker 1954). In this case, we're working on deviations from growth under the assumed Ricker model. The model fits similarly to the previous configuration, but the primary difference can be observed outside of the range of observed data. This configuration helps linearly ground the fishery model abundance to zero as simulated removals approach the total population size. Without this prior, it's possible that outside of the observed range of the data, the abundance levels out to the flat prior where the population may never reach zero (and can result in extraordinarily high landings under simulated high harvest rates).

3.2.1.2 Embedding Dimension

EDM embedding dimension E is limited by the length T of the time series. An approximate maximum embedding dimension is $E \le \sqrt{T}$. In the case of continuous seasonal data, the maximum embedding dimension is larger since the time series T is longer. Models were configured using Summer and Fall seasons as continuous time steps throughout a year and as a population-specific level within a hierarchical EDM, which will be explained in further detail below. The embedding dimension is defined as the number of population lags m (and covariates z if included) plus one, E = m + z + 1. For White Shrimp, the first year of the LDWF survey was 1980, resulting in 43 years of data, and a maximum embedding dimension of approximately 6 on an annual scale.

3.2.1.3 Hierarchical Model Scaling

Prior to fitting EDM models, all input data are standardized to a mean of 0 and standard deviation of 1. In the context of EDM, the term 'populations' is used to define data aggregations where information is expected to be informative. For White Shrimp, data aggregations and resulting populations that could be used to delineate levels of EDM are defined at the start of *Section 2*. For systems with multiple populations, these could be fit within a hierarchical EDM or independently.

In hierarchical models, the data must be scaled globally or locally across populations. For global scaling, the data across populations are expected to have the same mean. For White Shrimp, global scaling is likely inappropriate for most strata defined here. For example, we never expect the abundance of Large shrimp to equal the abundance of Small shrimp as would be implied by global scaling. Local scaling allows us to scale the data within the defined population time series of available data for each respective lag of population abundance or covariate. Both global and local scaling are applied within each predictor, not across all data. For example, each predictor is scaled to a mean of 0 and standard deviation of 1 for each lag and covariate. For global scaling, all data from all populations are used to scale the data; for local scaling, this is done within populations.

In independent models, definition of global or local scaling is obsolete because all data are scaled to a mean of 0 and standard deviation of 1. Independent models were tested for all data aggregations to ensure information was gained through the increased complexity and shared information from hierarchical models and with dynamic correlation.

3.2.1.4 Dynamic Correlation

Dynamic correlation ρ is defined as the degree to which the EDM population dynamics are correlated. This quantifies the similarity of population responses across predictor space and ranges from 0 to 1. Populations in hierarchical models will share the same embedding parameters and inverse length scale parameters (this includes models with $\rho=0$, or independent dynamics). A dynamic correlation $\rho=1$ means the dynamics of each population are identical. In other words, we assume that all delay vectors come from the same attractor. If fitting a single population or independent model, ρ reverts back to the mode of the prior, 0.5.

In hierarchical models, the dynamic correlation can be fixed or estimated. In cases where dynamic correlation is set to 0 within a hierarchical model, this will still yield different results when compared to independently fit models. This is because the hierarchical model shares information among the estimated length scale parameters ϕ for each embedding parameter.

3.2.1.5 Length Scale

Length scale parameters ϕ and the number of model inputs (i = m + z) define the complexity of the function represented by the GP. Each model input i incorporates an additional dimension of space, and their associated length scale parameter ϕ_i defines the wiggliness in that dimension. Low values of ϕ indicate stiff and mostly linear relationships, and large values of ϕ indicate more nonlinear relationships. A model with a single input and large ϕ_1 would have many degrees of freedom, while a model with many inputs but all ϕ_i close to 0 would have relatively few degrees of freedom (Tsai et al. 2024).

3.2.1.6 Data Transformations

Possible data transformations on the population are defined below. This is referred to as 'ytrans' in the GP-EDM R Package, but was defined as X_t above. This is the transformation that is applied before fitting the model.

- none: no transformation
- log: log transformation $(log(X_t))$
- grl: log difference transformation $(log(X_t/X_{t-1}))$
- gr2: log difference transformation on escapement $(log(X_t/(X_{t-1}-q*C_{t-1})))$

3.2.1.7 Covariates

The underlying theory of EDM is that lags of the population have information on population drivers embedded within them (Munch et al. 2020). It is possible to include some covariates directly in EDM that are believed to influence population abundance. In the case of Gulf penaeid shrimp, economic conditions have had a massive impact on the domestic fishery, which in turn directly influences the amount of shrimp left in the water. Additionally, it has been hypothesized that environmental drivers such as salinity and temperature in the shrimp nursery grounds may have a direct impact on recruitment to the population the following year (Turley et al. 2023).

While covariates have the potential to improve model fits and short-term predictive accuracy, relying on lags of the population alone for estimating the biological MSY is simpler from an operational standpoint. Including covariates in the model requires making some assumption

about the future states of that covariate in projections, which cannot be done with high confidence in this context. In addition, some of the variables considered may contain some level of covariation which the model is not set up to account for in its present form.

3.2.1.8 Cross Validation

Two different cross validation approaches were explored to evaluate prediction accuracy: "leave time out" and "sequential". Prediction method "leave time out" leaves out all data points (i.e., survey data, catch, covariates) taken at the same time across all populations where population is specified within hierarchical models. The "sequential" prediction method leaves out all future time points across all populations where population is specified. In both of these methods, training data are iteratively omitted for the predictions, but the inverse length scales and variances used are those obtained using all of the training data under the originally fit model. We anticipate that "sequential" would perform worse when compared to "leave time out". Both cross validation approaches were applied to all model configurations, but ultimately the "sequential" method was preferred for model selection because our ultimate objective is to project landings and harvest rates into the future in order to accurately estimate the system's maximum sustainable yield for fishery management.

3.2.2 Goodness of Fit

Goodness of fit was measured through the estimation of R^2 .

In sample fit statistics for each prediction method:

- R^2 proportion of variance explained by model (independent or hierarchical)
- ullet R_{pop}^2 proportion of variance explained for each population within a hierarchical model
- R_{scaled}^2 proportion of variance explained by a hierarchical model, centered and scaled by population means
- rmse root mean square error
- df degrees of freedom, trace of the smoother matrix

Out-of-sample fit statistics for each prediction method:

- R_{out}^2 out-of-sample R^2
- R_{outpop}^2 out-of-sample R_{pop}^2
- $R_{outscaled}^2$ out-of-sample R_{scaled}^2
- rmse_{out} out-of-sample rmse

These fit statistics measure the models' overall performance and ability to perform outside of the training data. Within hierarchical models, population-specific R_{pop}^2 metrics measure the model's ability to track the individual populations. For example, a model may be able to track one population well, but may fit another poorly. These population-specific R_{pop}^2 metrics were centered and scaled around their respective model means in the R_{scaled}^2 fit statistics to more appropriately measure the overall model performance. Population-specific R_{pop}^2 and R_{scaled}^2

statistics were compared to R^2 statistics obtained from independent model fits of each population to ensure that the complexity of the hierarchical model was warranted (i.e. improved overall prediction skill).

3.2.3 Estimated Parameters

Parameters estimated and priors specified in GP-EDM are defined below.

- ϕ_1 : ϕ_i length scale parameters for 1: *i* where *i* is the total *m* lags and *z* covariates (i = m + z); priors are set such that the expected number of local extrema for each ϕ_i is 1 (Munch et al. 2017)
- V_{ρ} process variance
- τ pointwise prior variance in f
- ρ dynamic correlation between populations where values range from 0 to 1, with 0-independent no correlation and 1- identical dynamics
- q- catchability scalar that translates the units of landings into units of survey CPUE

The relative magnitude of the pointwise prior variance τ and process noise V_e gives information on how important the function is relative to the noise. Process variance is represented as a percentage of the total variance, whereas the pointwise prior variance cannot be directly translated to variance percentage because it interacts with the length scale parameters. If the model is purely deterministic, $V_e = 0$ and $\tau \approx 1$. If the model is not fitting the data well, τ is small and the process variance is close to 1.

Catchability could be estimated jointly (q=shared) or separately for each population in each model configuration. In some instances, the model obtained very good fits, but estimated catchability q = 0 and ignored the landings altogether. For the purposes of our work here, the link to landings is critical. To select a representative model for estimating MSY, the models were filtered to exclude any model where catchability < 0.001 (where the observed catchability in the data were typically above 0.01).

3.2.4 Estimating Maximum Sustainable Yield (MSY) with EDM

Maximum Sustainble Yield (MSY) estimates were generated following the methodology outlined in Tsai et al. (2024). Harvest rates ranging from 0:1 were projected into the future and an average of the long-term dynamics were taken for each population, then added up to obtain estimates of long-term landings. These averages were used to identify the harvest rate that maximizes landings. Models that were configured seasonally required landings and associated harvest rates to be translated to annual scales. Translating catch from a seasonal to an annual time scale was fairly simple

$$C_t = 2 * C_{t/2}$$

where t is defined as one year here, and t/2 represents 2 seasonal steps per year. Annual harvest rate U_t was estimated from a seasonal harvest rate $U_{t/2}$ as

$$U_t = 1 - \left(1 - U_{t/2}\right)^2$$

where the new estimated harvest rate U_t captures the portion of the population (0:1) removed via landings over the course of a year. Here, the estimated long-term biomass associated with the rate of removals does not need to be changed. The annual harvest rate U_t was further translated to an annual fishing mortality rate $F_t = -ln(1 - U_t)$. This allows for the calculation of the more familiar benchmark F_t/F_{MSY} , which is a measure of overfishing (estimated to be occurring if $F_t/F_{MSY} > 1$).

3.2.5 Model Diagnostics

Models were diagnosed and deemed reliable based on a set of criteria defined below. This methodology worked well for all Gulf shrimp species assessed within SEDAR 87. These decisions were applied to 'no covariate' models, since assumptions on the cyclical nature of environmental variables and the relationship between harvest rate and economic variables would be required for projections. It was determined that these assumptions should be avoided for the purposes of defining biological maxima if possible. The projection period was initially set to 50 timesteps then extended to 80 to ensure the reference points had stabilized before taking an average. The duration over which to average was determined by the length of a cycle, which was typically driven by the seasonal time steps in the model if present. The estimate of MSY is sensitive to setting an appropriate projection period that ensures the population has stabilized and an appropriate save interval that ensures only complete cycles are clipped, the latter ensures the estimate is not biased high or low (as would be observed if the time step just outside of a completed cycle is increasing or decreasing, respectively).

3.2.5.1 Model Fitting Performance

Model performance was determined by considering the suite of Goodness of Fit parameters defined above. The top 30 models from the hierarchical overall R_{out}^2 and top 30 models from the $R_{outscaled}^2$ were pulled, and any overlapping models were considered. The top 5 from each of these criteria and the top 5 aggregated Gulf-wide models were considered to evaluate what was gained from added complexity.

3.2.5.2 Model Projection Performance

Projection performance was evaluated to ensure models extrapolate to MSY in a reasonable way. Model selection was already performed with this goal in mind when relying on predictmethod=sequential to obtain fit statistics. Additional diagnostics were developed to cull out unreasonable models. This included removing models that maximized catch at U=1, which generally happened when models would predict that the population returns to the flat prior outside of the observed range of the data. These models were often paired with unrealistically high catch estimates due to the coupling of extreme harvest rates with populations that did not always ground to zero. It is intuitively not sustainable to remove the entire population, so these models were removed. Unrealistically high estimates of MSY were defined as greater than ten times the highest historic landings.

3.2.5.3 Model Robustness

From the remaining set of models that (1) had good fits, (2) did not solve on a bound (U = 1), and (3) did not estimate MSY at greater than 10x historical landings records, a retrospective pattern analysis was carried out where 1 to 5 time steps were peeled back and MSY was re-

estimated. The Model Projection Performance selection criteria defined above were applied to each of these iterations. If any iteration failed, it was dropped from further consideration. This resulted in a final selection that balances model complexity and relative stability.

4. Stock Assessment Model Results

4.1 JABBA Results

4.1.1 Model Fit and Diagnostics

Diagnostic results for the top performing JABBA model runs are presented in *Figure 20*. Out of the four models retained, two showed signs of poor convergence. All models showed a persistent, increasing trend in process error deviations, with the two runs that did not allow for any additional observation error (runs 13 and 16) exhibiting strong deviations from the zero line, which indicates that changes in biomass diverge from the model expectations. Model runs were generally consistent (*Figure 21*) but none showed any prediction power (the hindcast cross validation results were poor with MASE >1) with the model systematically underestimating the index value in years 2018 and beyond (*Figure 22*).

The models were fairly insensitive to the prior assumption made about r but highly sensitive to the prior assumption made about initial depletion. Allowing additional observation error on the index did not change the point estimates considerably but did result in much higher uncertainty for all estimated parameters and derived quantities. Detailed figures showing the results of each diagnostic test are reported for run 16 (Figure 21, Figure 22, Figure 23).

4.1.2 Estimated Parameters and Derived Quantities

Estimated parameters for these models are provided in *Table 3* and *Figure 24*. For the models being considered here, each MSY was estimated between 70-80 million pounds of tails, a consistent estimate given the range of parameterizations (*Table 4*). There is an extremely wide range of estimates of unfished biomass shown in the surplus production models being considered (*Figure 25*), and the estimated time series of B/B_{MSY} is sensitive to the initial depletion prior (*Figure 26*). Most models dip below B/B_{MSY} periodically throughout the assessment time period until the mid-2000s (*Figure 27*), when the fishery began targeting almost exclusively Large shrimp (*Figure 7*).

Most model posteriors did not deviate significantly from the priors as there was not much contrast in the data to inform the underlying surplus production model (*Figure 28*). There was also evidence of bimodality in the posteriors for K and q, suggesting two alternative solutions and general model instability (*Figure 28*).

4.2 EDM Results

Over 5,500 model configurations were evaluated for White Shrimp to explore assumptions and ensure that results from the various iterations made sense. Up to the maximum embedding dimension was considered, with preference given to simpler models where possible. Estimated parameters, model fits, and projection capabilities are discussed below, resulting in the recommendation of a single model by the end of this section.

4.2.1 Model Configurations

Model configurations were examined to test assumptions and ensure results were as expected. The impact of using the 'sequential' method when defining the training dataset for prediction accuracy is shown in *Figure 29*, where 'leave-time-out' almost always yielded a higher out-of-sample R_{out}^2 fit. In hierarchical models, large differences in population means could artificially inflate the R_{out}^2 metric. Therefore, metrics were calculated to estimate goodness-of-fit that were centered and scaled around the population mean, $R_{scaledout}^2$. Hierarchical out-of-sample R_{out}^2 generally yielded a higher value than the out-of-sample scaled by population-specific fits, $R_{scaledout}^2$. With these models, the goal is to fit and project each population within the model well, and $R_{scaledout}^2$ was the primary metric used to gauge model fits going forward.

Models with local scaling were considered over global scaling for all model configurations since we don't expect the populations as defined here to ever be equal (except for models with one "population" where global scaling is inherent). The distribution of out-of-sample scaled $R_{scaledout}^2$ fit statistic was shown across all model configurations (embedding dimension, population, y transformation) (*Figure 30*).

Some of the reported R^2 metrics were associated with models that ignored landings (i.e. $q \approx 0$). Figure 31 shows the distribution of R^2 after these models were removed. From the set of models that account for landings, additional models were excluded due to the fact that they included covariates. In Figure 32, information can be inferred about the relative scales of population sizes and landings, where model configurations fit better to distinct catchabilities (e.g., different scales between populations and landings) compared with models that assumed shared catchabilities (e.g. similar scales between population and landings). This figure shows the model configurations that were analyzed for fit and eventual MSY estimation.

4.2.2 Model Fit and Residual Analysis

From the set of models described in the previous section, the procedures outlined in *Section 3.2.5.1* were applied, i.e. ranking the models by out-of-sample prediction accuracy for the model as a whole (R_{out}^2) , scaled by population $(R_{outscaled}^2)$, or both (*Section 3.2.2*). This resulted in 59 models going through MSY estimation and further model diagnostics (*Table 5*). These models had out-of-sample prediction accuracies ranging from 0.336 up to 0.87. Scaled population R_{scaled}^2 metrics ranged from 0.008 up to 0.484, where a zero here would indicate that one population prediction was no better than a random forecast. These were overall very good fits to the data, and in-sample fit statistics were even greater.

4.2.3 Model Diagnostics

The subset of 59 models with the best fits was further reduced down to 5 models after testing for projection ability and model robustness as outlined in *Section 3.2.5* (*Table 6*). The remaining models were all size class models with an annual time step except for one size-aggregated annual model. All hierarchical models were locally scaled, had separately estimated catchability parameters, and had a linear prior to ground the model to zero outside the observed range of the data as harvest rates approached 1. Both of the models with no scaling on the predictor variable (y_t) were characterized by instability, with a few peels solving for MSY at U = 1, where estimates spiked up to well over 10x historical record landings. The 3 remaining models all had

the gradient transformation on escapement for the predictor variable (y_t) and were were identically parameterized with different embedding dimensions: E=3,4,6. The model with E=3 (WSH_C4160), was the most unstable, with estimated MSY increasing by 300% for one of the peels and all others remaining within approximately 10% of the original estimate. This model was removed from consideration at this point. The model with E=6 (WSH_C20128) estimated the current harvest rates to be approaching and occasionally exceeding MSY with a smaller estimate of standing stock biomass, conflicting with the majority of other model run outputs. This resulted in the preferred model E=4 (WSH_C4182), which appeared to appropriately capture the dynamics of the system. This run estimated MSY greater than the historical landings record with a larger standing biomass, which aligns with how we understand the fishery. Top performing model parameterizations are summarized below, where WSH_C4182 was preferred due to its simpler embedding dimension and more consistent results compared to the other models.

Run	Catchability	Population	Time Step	Lags	Scaling	Transformation
C20128	Distinct	Size (S,M,L)	Annual	6	Local	gr2
C4182	Distinct	Size (S,M,L)	Annual	4	Local	gr2

Variable harvest rate projections of CPUE by size class for the recommended model are shown in *Figure 33 - 35* and associated landings are shown in *Figure 36 - 38*. These data series were used to generate average biomass and landings under all harvest rates 0:1 in *Figure 39* and *Figure 40*. The total metrics for B_{MSY} and MSY are shown in *Figure 41* and *Figure 42* where dashed lines represent the annual rate at MSY. The horizontal dotted line on the MSY figure shows the maximum landings ever caught by the fishery, 85.1 million pounds of tails in 2006, which is slightly less than the projected MSY here, 87.8 million pounds of tails.

4.2.4 Estimated Parameters and Derived Quantities

Estimated parameters from the top-performing model are shown in *Table 7*. The function-space complexity is defined jointly by the length scales, which define the degree of nonlinearity, and the covariance matrix, which can open up the ability of the model to vary within a smoother space. The estimated length scale parameters ϕ_i are all approximately equal to 1 or less and are linear and smooth for all populations in the model (*Figure 43 - 46*). The length scale parameters on lags 3 and 4, ϕ_3 and ϕ_4 , are flat and effectively act as scalars to the model. The pointwise prior variance was estimated to be 0.416 and was exceeded by the function process variance of 0.821, indicating a large amount of variability unexplained by the model. The dynamic correlation of the model was 0.864, indicating a high correlation between these data, which we can observe visually most easily in *Figure 4* and *Figure 7*. These size populations had distinct catchabilities that translate fishery removals to the units of the LDWF survey (number of shrimp per 10 minute tow divided by 10 million pounds of tails): Large q = 0.021, Medium q = 0.627, and Small q = 3.767. These vary markedly because of the distinct relative scales between population sizes and realized landings (e.g. Large is consistently the rarest population in the survey, but is the most common size class observed in the landings in recent years).

The R^2 statistics very high for the overall metrics compared to the population-scaled metrics, indicating a poor fit for at least once of the size classes (*Table 8*). Here, the Large and Small

populations performed similarly $R_{popout}^2 \approx 0.20$, while Medium pulled the average down with $R_{popout}^2 = 0.09$. These values contributed to the $R_{outscaled}^2 = 0.174$ scaled by population means, while out-of-sample $R_{out}^2 = 0.856$, indicating the latter was likely inflated by the magnitude of differences in population means. Derived population benchmarks and associated rates are shown in *Table 8* alongside model fit statistics. Annual MSY was estimated as 87.8 million pounds of tails, occurring at $F_{MSY} = 0.896$ where the population biomass at this rate is $B_{MSY} = 148.35$ million pounds of tails.

4.2.5 Fishing Mortality

Estimated fishing mortality rates through time are shown in *Table 9*. In 2022, the stock experienced 15% F_{MSY} and the stock size was ~2.5x B_{MSY} . The highest rates of fishing mortality were observed in the late 1980's prior to the economic collapse of the fleet due to aquaculture imports, but is not estimated to have ever experienced overfishing ($F/F_{MSY} < 1$).

4.2.6 Biomass and Abundance Trajectories

The White Shrimp stock was estimated to have dipped below B_{MSY} a few times throughout the time series, during high landings in both the late 1980s and the early 2000s. This could be explained by the oscillating nature of this stock, where landings in the late 1980s and early 2000s were high, particularly for Large shrimp, but the population was in a trough, resulting in $B/B_{MSY} < 1$. Given the oscillating nature of EDM, it is possible that when using averaged MSY projections, the true sustainable fishing levels in any given year could be above or below the average MSY, but it is not expected to be an issue unless the system begins chronically dipping below sustainable levels. Fits of the preferred model are shown in *Figure 47* and *Figure 48*.

5. Discussion

EDM is particularly suitable for studying populations that exhibit non-equilibrium dynamics and nonlinear state-dependent behavior (i.e. where interactions change over time and as a function of the system state). JABBA relies on very rigid SPM assumptions about stock and fishery dynamics that likely do not hold true for shrimp. EDM had better performance metrics and diagnostics than JABBA, resulting in an EDM model being recommended for providing management advice.

The JABBA models were generally poor and limited by the overarching constraints of surplus production models which aggregate dynamics, not accounting for size or spatial differences. The models were highly sensitive to the prior specification for initial depletion and showed signs of instability and little to no predictive power. This poor model performance was likely driven by the limited contrast present in the data, with landings exhibiting a one-way trip throughout the time period of the assessment and CPUE not appearing to respond to this increase in catches. In addition, it is likely that White Shrimp stock dynamics are driven more by environmental and economic factors than by the catches, which could lead the stock to appear to respond to the fishery in unexpected ways (e.g. large changes in abundance despite no changes in catch or abundance and landings increasing in unison). The Gulf White Shrimp fishery landings size compositions have changed considerably through time (*Figure 8*) due to global market conditions and increasing demand and prices yielded for Large shrimp. This likely causes a mismatch between the time series of CPUE and catches in terms of what each is indexing,

further confusing the size aggregated model. Additionally, as the domestic fleet consolidated, larger and more efficient vessels remained and could be trawling in a different habitat compared to the historic distribution of the fleet. These factors are all justifications against using surplus production models that assume catch levels reflect only changes in stock abundance and that patterns of exploitation are primarily driven by shrimp availability rather than environmental or economic considerations.

EDM models showed good diagnostics and prediction accuracy. The biomass of the White Shrimp population and removals were modeled and predicted well. Size-structure was included through the use of populations within a hierarchical GP-EDM, which further improved the model fits. There was a disconnect in the relative presence of size classes between the survey (where Small was most abundant) and the fishery (where Large was the most abundant in recent years) which may have contributed to the larger process variance. Through this work, the incorporation of distinct catchabilities in the GP-EDM package was implemented, but capturing the shifting catchabilities through time (or before and after the economic transition in the mid-2000s) may improve the ability of the model to explain total variance.

One caveat of the current EDM configurations explored here is there is no feedback loop from smaller size classes to larger size classes. For example, there is no penalty on Medium and Large shrimp for removing too many Small too early under a high harvest rate. In reality, a harvest rate that maximizes Small shrimp may cause a negative feedback loop on Large shrimp that is not accounted for here. In some simulations, the peak landings for Large shrimp was at a much lower harvest rate than the Small, and when aggregating these size classes to approximate a total MSY, it is feasible that the realized Large shrimp landings would be lower due to the lack of Small shrimp growing out to Medium and Large size classes. Accounting for this negative feedback loop through mixed-age configurations is possible (Dolan et al. 2023), but it is complicated by mixing landings across calendar years to fit to population escapement, which would markedly increase management complexity, perhaps unnecessarily. The recommended EDM configuration here maximized landings of Large and Small size classes at approximately the same harvest rate with the landings for Medium maximized at a slightly higher rate, removing the immediate need to explore this caveat further.

EDM was able to capture the cyclical nature of shrimp population abundance, resulting in a more accurate population model. Lags of the population retain information on sometimes immeasurable drivers, including abundance of predators and some environmental influences. Direct inclusion of environmental and economic covariates improved model fits further, but they were not used in the final model because additional assumptions would be required on the future state of the industry and environment. Furthermore, relationships between the simulated harvest rates and these covariates would need to be addressed, and may respond in unexpected ways. Given the goal of providing a biological MSY estimate for this fishery, biological models only were used for this purpose. The models with covariates may serve other purposes and could be used to predict year-ahead abundance and landings more accurately than the model with lags alone, particularly for those tied to economic drivers.

Finally, providing management advice for this fishery using static estimates of MSY may not be appropriate due to the highly cyclical nature of this stock which is not fully captured in a long-term average. The model itself captures the dynamics, but the methods to obtain MSY through a long-run average do not. In high productivity years, the fishery may be able to harvest more than

the average MSY, in low productivity years, they may push the stock into an 'overfished' status (see late 1980s, early 2000s). To provide management advice for a population with such large estimates of sustainable landings, the long run average should be used to ensure that the stock does not undergo overfishing. In the event of improved economic conditions where the fleet expands and under prevailing environmental conditions, this assumption could be revisited and management advice could be provided on a finer scale. Updating the model with seasonal inputs as they are available could account for the peaks and dips in productivity, allowing the fleet to take advantage of high productivity years or potentially sit out low productivity years. Because the fleet is mainly limited by the economics of the fishery, these kinds of model explorations are recommended as a future research recommendation.

6. Research Recommendations

The models provided in this report are sufficient to provide management advice for the stock. However, should future research funding become available, we have provided suggestions below.

Potential improvements to the modeling framework include accounting for removal of shrimp as it pertains to harvest rates that are optimized at varying size classes. Creating a feedback loop that appropriately represents the removal of larger shrimp that may not contribute to future generations as well as the removal of smaller shrimp that may not grow into Large shrimp should be accounted for. Sensitivities of these potential feedback loops and their impact on estimating optimal harvest rates should be investigated in both directions (i.e. Large to Small and Small to Large impacts).

Additional research into covariates may also be investigated. Direct inclusion of covariates generally resulted in improved model fits and could likely improve forecasting efficiency for trends of abundance. To forecast MSY, covariates would need to be projected into the future. For environmental covariates, the cyclical nature of these trends would need to be captured. For economic covariates, the relationship with projected harvest rates would need to be explicitly defined.

Implications of the LDWF survey capturing mostly Small shrimp in conjunction with the fishery capturing mostly Large shrimp should be investigated as it pertains to catchability estimation and resulting estimates of escapement. It is suspected that this was the primary driver for a large process variance in the model.

7. Acknowledgements

The SEDAR 87 Gulf White Shrimp Benchmark Assessment would not have been possible without the efforts of the numerous NMFS, SEFSC, SERO, and GMFMC staff along with the many academic, research partners, and stakeholders involved throughout the Gulf listed in Section 1.1.3.

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9. Tables

Table 1: LDWF CPUE in number of shrimp per 10min trawl for White Shrimp by size.

Year	Large	Medium	Small
1980	0.10	2.69	22.13
1981	0.22	3.74	17.50
1982	0.13	2.33	15.86
1983	0.09	1.72	17.05
1984	0.16	3.37	18.34
1985	0.14	3.23	21.28
1986	0.28	4.78	24.28
1987	0.14	3.60	20.58
1988	0.03	1.45	10.20
1989	0.06	1.57	10.84
1990	0.08	2.15	15.80
1991	0.08	1.98	22.06
1992	0.07	2.42	19.02
1993	0.09	1.81	31.29
1994	0.12	1.69	30.86
1995	0.11	2.68	29.48
1996	0.11	2.17	17.62
1997	0.07	1.53	23.57
1998	0.08	1.72	28.48
1999	0.03	1.41	24.38
2000	0.07	2.76	28.18
2001	0.08	1.58	15.46
2002	0.07	1.54	14.59
2003	0.08	1.93	20.04
2004	0.12	2.90	32.47
2005	0.20	4.89	29.94
2006	0.66	6.36	47.48
2007	0.26	4.32	42.34
2008	0.35	5.39	34.96
2009	0.36	5.74	45.87
2010	0.53	4.93	39.20
2011	0.50	4.84	21.35
2012	0.32	3.52	31.90
2013	0.22	2.65	27.33

Table 1 Continued: LDWF CPUE in number of shrimp per 10min trawl for White Shrimp by size.

Year	Large	Medium	Small
2014	0.14	2.26	20.39
2015	0.30	3.87	26.88
2016	0.11	3.24	30.74
2017	0.13	4.61	21.86
2018	0.14	2.44	30.11
2019	0.08	1.91	23.35
2020	0.23	2.96	39.77
2021	0.11	2.80	32.67
2022	0.42	7.31	51.52

Table 2: Landings of White Shrimp in 10 million pounds of tails by size.

Year	Large	Medium	Small
1980	1.13	1.53	1.61
1981	1.68	1.60	1.33
1982	0.99	1.46	1.47
1983	1.17	1.81	1.25
1984	1.63	2.66	1.31
1985	1.56	2.68	1.64
1986	1.79	3.13	2.08
1987	1.32	2.40	1.56
1988	0.85	2.26	1.36
1989	0.85	1.40	1.36
1990	1.30	1.84	1.22
1991	1.40	1.61	1.52
1992	1.10	1.98	1.65
1993	1.03	1.58	1.25
1994	0.95	1.80	1.78
1995	1.43	2.07	1.36
1996	1.04	1.58	0.93
1997	0.93	1.58	1.34
1998	1.73	2.16	1.52
1999	1.48	1.95	1.98
2000	1.85	2.21	3.00
2001	1.66	1.50	2.23
2002	1.90	1.58	1.76
2003	1.95	1.66	2.38
2004	2.17	2.16	2.28
2005	2.34	2.11	1.89
2006	3.44	2.42	2.63
2007	2.60	1.89	2.01
2008	3.10	1.60	1.78
2009	3.11	2.15	2.10
2010	2.17	1.81	1.81
2011	3.00	1.26	1.43
2012	2.48	1.90	2.24
2013	2.28	1.33	1.93

Table 2 Continued: Landings of white shrimp in 10 million pounds of tails by size.

				_
Year	Large	Medium	Small	
2014	1.89	1.74	2.38	-
2015	2.04	1.58	1.72	
2016	2.55	2.02	2.31	
2017	2.58	2.09	2.20	
2018	1.98	1.61	1.56	
2019	2.58	2.26	1.72	
2020	2.41	1.88	1.58	
2021	2.41	1.83	2.03	
2022	3.15	2.08	1.58	

Table 3: White Shrimp parameter estimates from JABBA where Runs are described using unique indentifiers (1:90), P indicates a Pella-Tomlinson surplus production curve with estimated shape parameter m, r is the relative level of the intrinsic rate of growth prior (M-Medium, H-High), psi is the initial depletion prior (0.9 low, 0.2 high), sig indicates whether additional observation error tau2 is estimated (T/F), and the last two numbers are the start year of the landings (1960). Median parameter estimates are provided with lower and upper credible intervals. K is reported in million lb tail weight.

Run	Parameter	Estimate	LCI.95	UCI.95
WSH 4 P rM psil0.9 sigT 60	K	1,064.70	521.66	2,382.11
WSH 4 P rM psil0.9 sigT 60	r	0.26	0.15	0.53
WSH 4 P rM psil0.9 sigT 60		0.20	0.00	0.00
	q na:		0.51	1.27
WSH_4_P_rM_psil0.9_sigT_60	psi	0.85		
WSH_4_P_rM_psil0.9_sigT_60	sigma2	0.01	0.00	0.04
WSH_4_P_rM_psil0.9_sigT_60	tau2	0.09	0.03	0.24
WSH_4_P_rM_psil0.9_sigT_60	m	1.33	0.72	2.39
WSH_13_P_rH_psil0.9_sigF_60	K	394.60	286.66	1,359.02
WSH_13_P_rH_psil0.9_sigF_60	r	0.59	0.41	0.83
WSH_13_P_rH_psil0.9_sigF_60	q	0.00	0.00	0.01
WSH_13_P_rH_psil0.9_sigF_60	psi	0.86	0.54	1.30
WSH_13_P_rH_psil0.9_sigF_60	sigma2	0.04	0.04	0.05
WSH_13_P_rH_psil0.9_sigF_60	tau2	0.00	0.00	0.01
WSH_13_P_rH_psil0.9_sigF_60	m	1.40	0.82	2.43
WSH_16_P_rM_psil0.9_sigF_60	K	589.32	358.16	1,473.57
WSH_16_P_rM_psil0.9_sigF_60	r	0.34	0.19	0.54
WSH_16_P_rM_psil0.9_sigF_60	q	0.00	0.00	0.00
WSH_16_P_rM_psil0.9_sigF_60	psi	0.85	0.54	1.30
WSH_16_P_rM_psil0.9_sigF_60	sigma2	0.04	0.04	0.05
WSH_16_P_rM_psil0.9_sigF_60	tau2	0.00	0.00	0.01
WSH_16_P_rM_psil0.9_sigF_60	m	1.05	0.60	1.84
WSH_76_P_rM_psil0.2_sigT_60	K	1,208.82	746.10	2,585.88
WSH_76_P_rM_psil0.2_sigT_60	r	0.24	0.15	0.42
WSH_76_P_rM_psil0.2_sigT_60	q	0.00	0.00	0.00
WSH_76_P_rM_psil0.2_sigT_60	psi	0.13	80.0	0.22
WSH_76_P_rM_psil0.2_sigT_60	sigma2	0.00	0.00	0.02
WSH_76_P_rM_psil0.2_sigT_60	tau2	0.09	0.05	0.17
WSH_76_P_rM_psil0.2_sigT_60	m	2.00	1.26	3.38

Table 4: White Shrimp reference points from selected JABBA models in Table 3. K, Bmsy and MSY are reported in million lb tail weight.

Run	K	Bmsy	Fmsy	MSY
WSH_4_P_rM_psil0.9_sigT_60	1,064.70	454.86	0.20	80.25
WSH_13_P_rH_psil0.9_sigF_60	394.60	168.02	0.43	74.57
WSH_16_P_rM_psil0.9_sigF_60	589.32	223.56	0.33	73.49
WSH_76_P_rM_psil0.2_sigT_60	1,208.82	604.39	0.12	72.30

Table 5: White Shrimp fit statistics for top performing models where run names are described by strata A:G, species, start year, landings units, shared catchability b (T/F), population, time step (YEAR2 is seasonal), embedding dimension E, scaling (global vs. local), y transformations (log, gr1, gr2, none), and linear prior (_ricker if used).

Run	R2_out	R2_outscale
A20052_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E6_global_ytransnone_ricker	0.370	0.370
A1828_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E5_global_ytranslog_ricker	0.366	0.366
A1696_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E5_global_ytransnone_ricker	0.364	0.364
A20056_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E6_global_ytranslog_ricker	0.360	0.360
A1916_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E3_global_ytransgr1_ricker	0.356	0.356
C3412_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E5_local_ytransnone_ricker	0.868	0.336
C20072_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E6_local_ytransnone_ricker	0.870	0.327
C3896_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E3_local_ytransgr1_ricker	0.870	0.298
C3368_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E3_local_ytransnone_ricker	0.869	0.301
C2840_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E3_local_ytransgr1_ricker	0.869	0.296
C3104_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E3_local_ytransgr2_ricker	0.868	0.278
C3126_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E4_local_ytransgr2_ricker	0.868	0.279
C2862_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E4_local_ytransgr1_ricker	0.867	0.292
C3940_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E5_local_ytransgr1_ricker	0.867	0.298
C3148_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E5_local_ytransgr2_ricker	0.865	0.278
C728_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E3_local_ytransgr1	0.865	0.216
C20120_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E6_local_ytransgr1_ricker	0.865	0.293
C750_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E4_local_ytransgr1	0.863	0.197
C20096_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E6_local_ytransgr2_ricker	0.863	0.273
C1784_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E3_local_ytransgr1	0.863	0.199
C1806_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E4_local_ytransgr1	0.863	0.202
C3676_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E5_local_ytranslog_ricker	0.861	0.221
C992_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E3_local_ytransgr2	0.861	0.057
C1014_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E4_local_ytransgr2	0.860	0.044
C1828_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E5_local_ytransgr1	0.859	0.203
C4160_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E3_local_ytransgr2_ricker	0.857	0.170
C20112_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E6_local_ytranslog_ricker	0.857	0.215
C20128_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E6_local_ytransgr2_ricker	0.857	0.211
C4182_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E4_local_ytransgr2_ricker	0.856	0.174
C20056_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E6_local_ytransgr1	0.855	0.191
C244_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E5_local_ytransnone	0.854	0.245
C772_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E5_local_ytransgr1	0.852	0.191
C1036_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E5_local_ytransgr2	0.849	0.008
C20024_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E6_local_ytransgr1	0.848	0.178
C20008_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E6_local_ytransnone	0.847	0.227

Table 5 Continued: White Shrimp fit statistics for top performing models where run names are described by strata A:G, species, start year, landings units, shared catchability b (T/F), population, time step (YEAR2 is seasonal), embedding dimension E, scaling (global vs. local), y transformations (log, gr1, gr2, none), and linear prior (_ricker if used).

Run	R2_out	R2_outscale
E20202_WSH1980_CPUEtail10mp_bshareF_GULFYEAR2_E6_global_ytransnone_ricker	0.484	0.484
E7218_WSH1980_CPUEtail10mp_bshareF_GULFYEAR2_E5_global_ytranslog_ricker	0.407	0.407
G21014_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E6_local_ytransnone	0.706	0.392
G21078_WSH1984_CPUEtail10mp_bshareF_SIZEYEAR2_E6_local_ytransnone	0.708	0.390
G16778_WSH1984_CPUEtail10mp_bshareF_SIZEYEAR2_E4_local_ytransnone_ricker	0.680	0.389
G14666_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E4_local_ytransnone_ricker	0.680	0.389
G14710_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E5_local_ytransnone_ricker	0.691	0.385
G10442_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E4_local_ytransnone	0.687	0.377
G14622_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E3_local_ytransnone_ricker	0.647	0.368
G12598_WSH1984_CPUEtail10mp_bshareF_SIZEYEAR2_E5_local_ytransnone	0.700	0.366
G10486_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E5_local_ytransnone	0.699	0.366
A1960_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E5_global_ytransgr1_ricker	0.351	0.351
G21158_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E6_local_ytranslog_ricker	0.665	0.345
C21072_WSH1980_CPUEtail10mp_bshareT_SIZEYEAR_E6_local_ytransnone_ricker	0.828	0.344
C21104_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E6_local_ytransnone_ricker	0.827	0.344
A20060_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E6_global_ytransgr1_ricker	0.343	0.343
C13412_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E5_local_ytransnone_ricker	0.826	0.341
G10398_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E3_local_ytransnone	0.637	0.341
C13940_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E5_local_ytransgr1_ricker	0.829	0.341
C21120_WSH1980_CPUEtail10mp_bshareF_SIZEYEAR_E6_local_ytransgr1_ricker	0.828	0.338
G15194_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E4_local_ytranslog_ricker	0.662	0.337
A860_WSH1980_CPUEtail10mp_bshareF_GULFYEAR_E3_global_ytransgr1	0.336	0.336
G20014_WSH1984_CPUEtail10mp_bshareT_SIZEYEAR2_E6_local_ytransnone	0.756	0.336
G2554_WSH1984_CPUEtail10mp_bshareF_SIZEYEAR2_E4_local_ytransnone	0.736	0.335

Table 6: Retrospective analysis of the White Shrimp MSY estimates for top tier performing models with increasing peels. $_0$ indicates the base model, and $_1:5$ indicates 1 through 5 time steps of data peeled back. The maximum landings throughout the history of the fishery is 85.12 million pound of tails (8.51 tail10mp), and MSY_factor is the amount of times MSY is over this value. MSY_drop indicates whether the average MSY estimate was greater than 5 or 10 times the historical high, and F_drop indicates that the model solved at harvest rate U=1 and was excluded from further consideration. MSY, and Bmsy are in millions of pounds of tails. Run details are included in the previous table.

Run	MSY	BMSY_mp	MSY_factor	MSY_drop5	MSY_drop10	F_drop
WSH_A1696_0	11.63	13.90	1.37	0	0	0
WSH_A1696_1	15.03	21.04	1.77	0	0	0
WSH_A1696_2	55,336.91	55,336.91	6,501.20	1	1	1
WSH_A1696_3	228,533.05	228,533.05	26,848.97	1	1	1
WSH_A1696_4	11,102.99	11,102.99	1,304.42	1	1	1
WSH_A1696_5	7.77	7.77	0.91	0	0	1
WSH_C4160_0	8.79	14.85	1.03	0	0	0
WSH_C4160_1	9.60	11.76	1.13	0	0	0
WSH_C4160_2	9.42	11.54	1.11	0	0	0
WSH_C4160_3	27.77	68.03	3.26	0	0	0
WSH_C4160_4	8.45	14.27	0.99	0	0	0
WSH_C4160_5	9.53	11.68	1.12	0	0	0
WSH_C20128_0	7.09	13.89	0.83	0	0	0
WSH_C20128_1	7.17	10.04	0.84	0	0	0
WSH_C20128_2	7.06	9.89	0.83	0	0	0
WSH_C20128_3	7.00	8.17	0.82	0	0	0
WSH_C20128_4	6.96	9.75	0.82	0	0	0
WSH_C20128_5	7.06	9.61	0.83	0	0	0
WSH_C4182_0	8.78	14.84	1.03	0	0	0
WSH_C4182_1	9.05	11.37	1.06	0	0	0
WSH_C4182_2	8.91	14.55	1.05	0	0	0
WSH_C4182_3	8.62	11.12	1.01	0	0	0
WSH_C4182_4	8.66	11.16	1.02	0	0	0
WSH_C4182_5	8.85	11.11	1.04	0	0	0
WSH_C21104_0	8.25	8.78	0.97	0	0	0
WSH_C21104_1	6,687,161.31	6,687,161.31	785,634.36	1	1	1
WSH_C21104_2	1,005,413.36	1,005,413.36	118,119.97	1	1	1
WSH_C21104_3	8.57	8.94	1.01	0	0	0
WSH_C21104_4	8.25	8.42	0.97	0	0	0
WSH_C21104_5	7.97	8.31	0.94	0	0	0

Table 7: White Shrimp parameter estimates for the top performing model.

Parameter	WSH_C4182
CatchabilityLarge	0.021
CatchabilityMedium	0.627
CatchabilitySmall	3.767
DynamicCorrelation	0.864
LengthScale1	1.216
LengthScale2	0.039
LengthScale3	0.000
LengthScale4	0.000
PointwisePriorVariance	0.416
ProcessVariance	0.821

Table 8: White Shrimp MSY estimates for the top performing model.

Statistic	WSH_C4182
MSY_10mptails	8.780
Fmsy	0.896
Umsy_annual	0.592
Bmsy_10mp	14.835
df	9.579
R2	0.887
R2Scaled	0.312
R2_outsample	0.856
R2Scaled_outsample	0.174

Table 9: White Shrimp status through time based on benchmarks from the recommended model. Land10mp- landings in 10 millions of pound of tails, Frate-fishing mortality rate, Best_10mp- estimate of population size in 10 millions of pound of tails, FFmsy- Frate relative to Fmsy, BBmsy- Best relative to Bmsy.

Year	land10mp	Frate	Best_10mp	FFmsy	BBmsy
1980	4.27	0.33	14.65	0.37	1.04
1981	4.61	0.33	20.95	0.37	0.90
1982	3.92	0.44	13.86	0.49	0.77
1983	4.22	0.37	11.28	0.42	0.79
1984	5.59	0.36	17.65	0.40	0.92
1985	5.88	0.39	17.24	0.43	1.03
1986	7.00	0.41	27.02	0.46	1.23
1987	5.28	0.36	17.65	0.41	1.02
1988	4.46	0.82	6.46	0.92	0.49
1989	3.61	0.66	7.96	0.74	0.52
1990	4.37	0.39	11.29	0.43	0.76
1991	4.52	0.33	12.86	0.37	1.01
1992	4.73	0.43	12.00	0.48	0.90
1993	3.86	0.19	15.33	0.21	1.39
1994	4.53	0.28	16.74	0.31	1.37
1995	4.86	0.22	17.17	0.25	1.35
1996	3.54	0.26	13.49	0.29	0.83
1997	3.85	0.28	12.07	0.31	1.06
1998	5.42	0.27	13.91	0.30	1.27
1999	5.41	0.41	10.23	0.46	1.08
2000	7.06	0.53	15.40	0.59	1.30
2001	5.39	0.79	10.20	0.88	0.72
2002	5.24	0.64	9.60	0.72	0.68
2003	5.99	0.61	12.30	0.68	0.92
2004	6.62	0.33	18.78	0.37	1.49
2005	6.34	0.28	25.36	0.31	1.47
2006	8.49	0.24	53.69	0.26	2.28
2007	6.50	0.21	30.12	0.23	1.97
2008	6.48	0.21	34.34	0.24	1.71
2009	7.35	0.20	38.42	0.22	2.18
2010	5.79	0.20	43.11	0.22	1.87
2011	5.69	0.27	36.76	0.30	1.12

Table 9 Continued: White Shrimp status through time based on benchmarks from the recommended model. Land10mp- landings in 10 millions of pound of tails, Frate-fishing mortality rate, Best_10mp- estimate of population size in 10 millions of pound of tails, FFmsy-Frate relative to Fmsy, BBmsy-Best relative to Bmsy.

Year	land10mp	Frate	Best_10mp	Best_10mp FFmsy	
2012	6.62	0.32	29.33	0.35	1.50
2013	5.54	0.31	21.92	0.35	1.27
2014	6.00	0.58	15.81	0.65	0.96
2015	5.35	0.28	27.46	0.31	1.30
2016	6.89	0.35	18.59	0.39	1.43
2017	6.87	0.45	19.48	0.50	1.12
2018	5.15	0.24	18.51	0.27	1.37
2019	6.56	0.38	12.93	0.42	1.06
2020	5.88	0.18	26.32	0.20	1.80
2021	6.27	0.29	18.11	0.32	1.49
2022	6.81	0.13	44.99	0.15	2.48

10. Figures



Figure 1: Map of the Gulf of America, where dark green is the Gulf defined by Gulf of Mexico Fishery Management Council boundaries, light green is Gulf international waters, and red is typically managed by the South Atlantic Fishery Management Council. Fishing areas 001 and 002 in their entirety were included in the analyses here per the recommendation of WP-06.

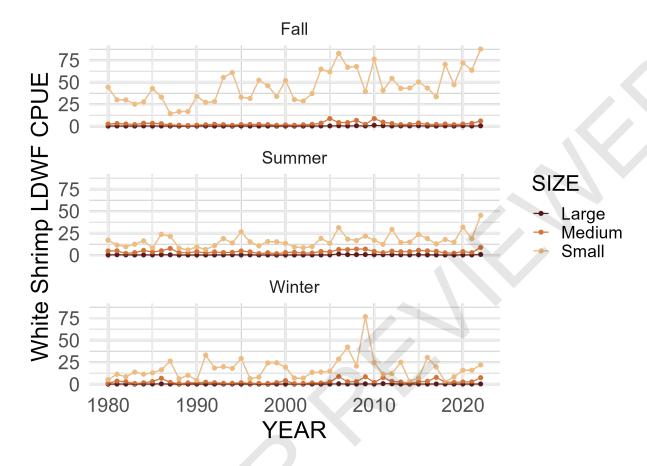


Figure 2: White Shrimp CPUE separated by size and season.

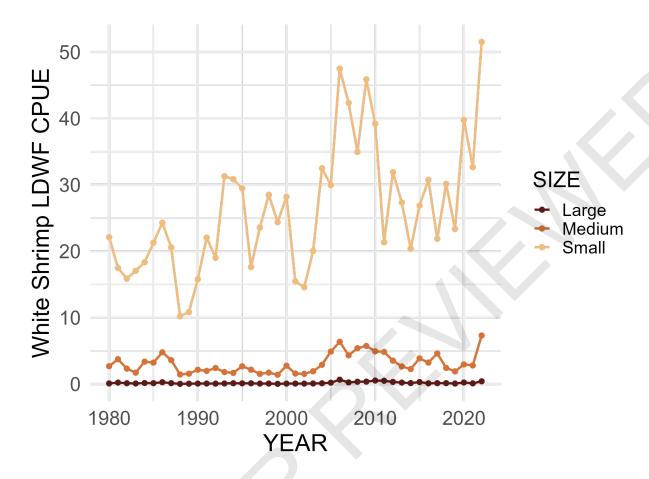


Figure 3: White Shrimp CPUE separated by size.

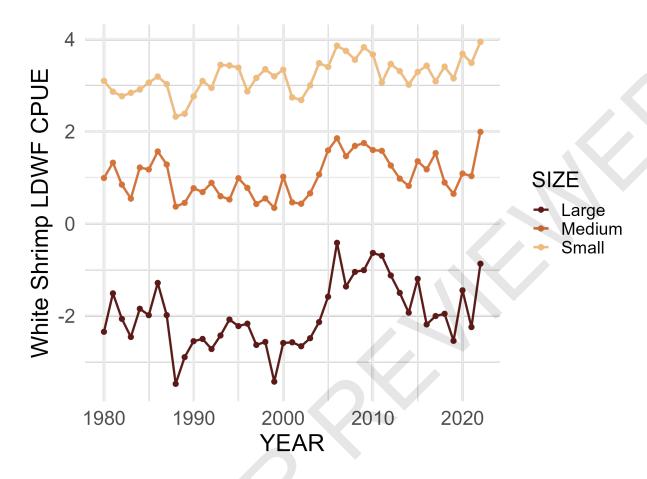


Figure 4: Log-transformed White Shrimp CPUE separated by size.

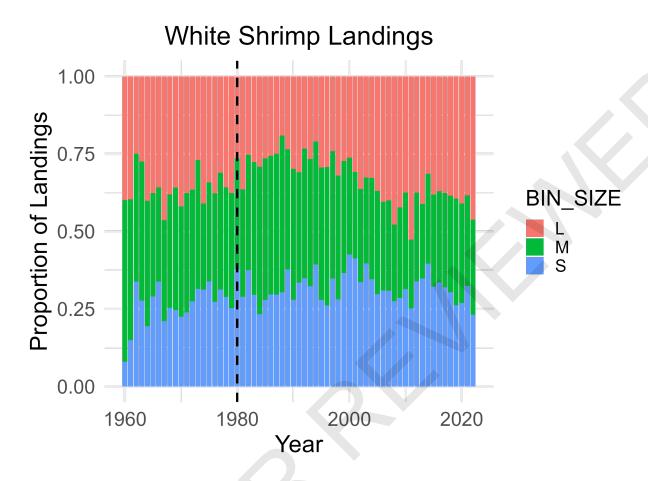


Figure 5: Proportion of landings by size class. The dashed line indicates the first year of the VAST index.

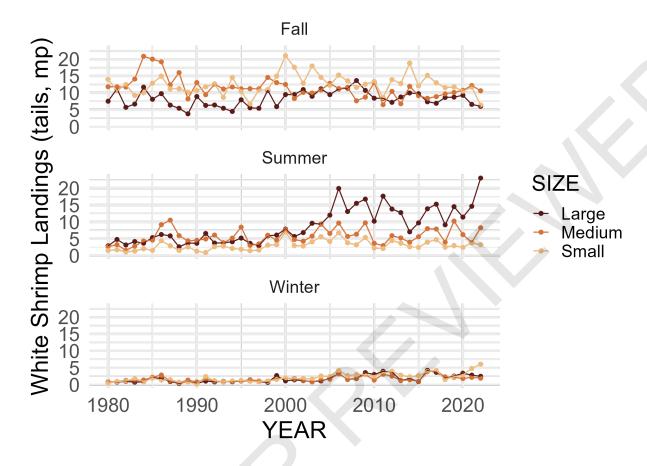


Figure 6: White Shrimp landings in millions of pounds of tails separated by size and season.

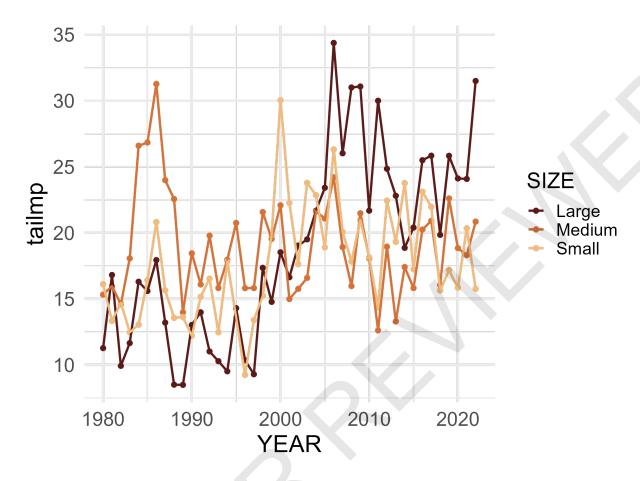


Figure 7: White Shrimp landings in millions of pounds of tails separated by size.

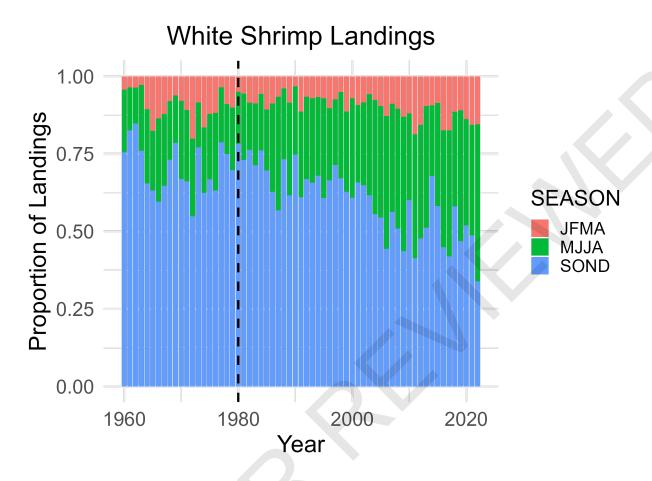


Figure 8: Seasonal distribution of White Shrimp landings.

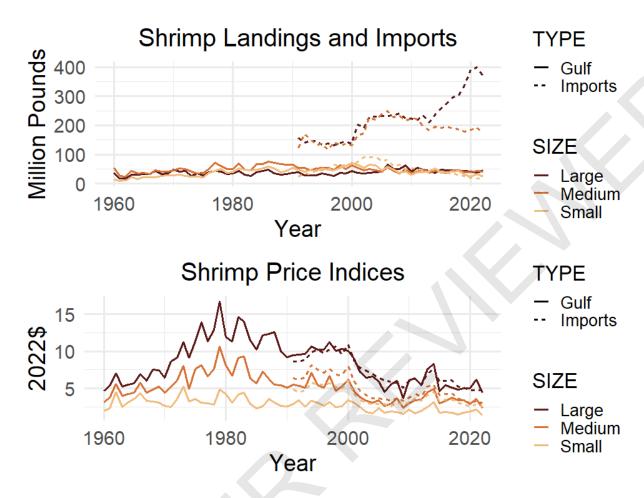


Figure 9: Domestic Gulf shrimp landings compared to global imports into the US by size category (top panel). This increase in supply has resulted in a crash of the ex-vessel price and domestic price index by size category, with all sizes decreasing, but Lsarge yielding the highest amount (bottom panel).

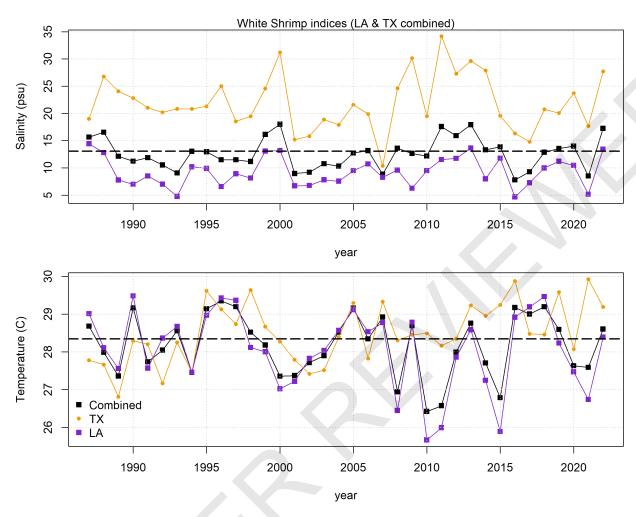


Figure 10: White Shrimp combined TX and LA environmental indices, truncated when TX data become available in 1987.

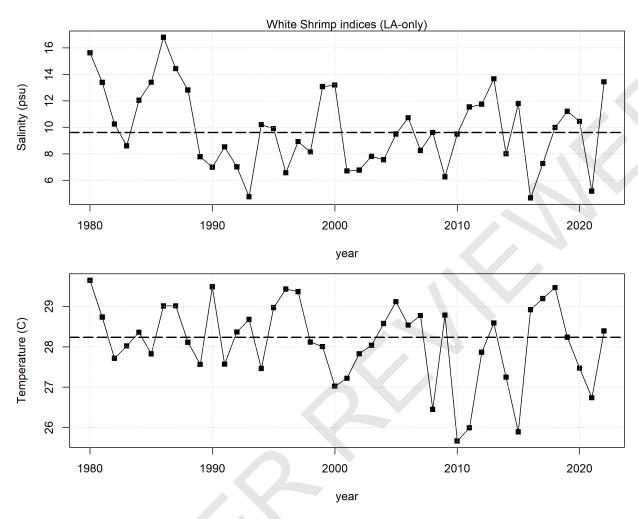


Figure 11: White Shrimp LA environmental indices to the beginning of the time series in 1980.

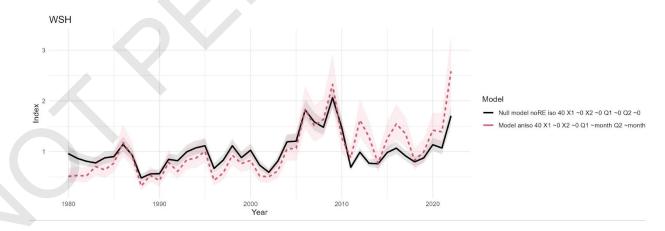


Figure 12: Final VAST index (red dashed line) and associated 95% confidence interval (red shading) incorporated into the JABBA model.

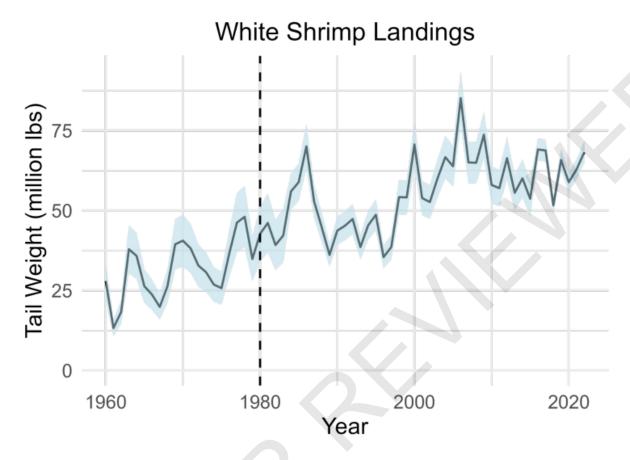


Figure 13: Final landings (blue line) and associated error (blue shading) input into JABBA. The dashed line indicates the start year of the index of relative abundance.

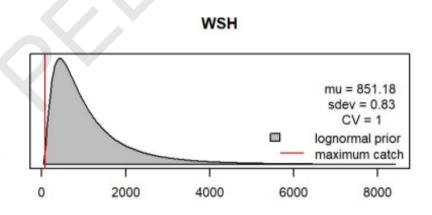


Figure 14: JABBA prior for carrying capacity, K, for all model configurations.

Pella-Tomlison shape parameter

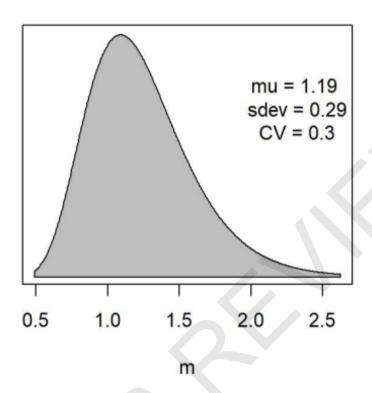


Figure 15: JABBA prior for Pella Tomlinson production function shape parameter, m, for all model configurations.

Process error

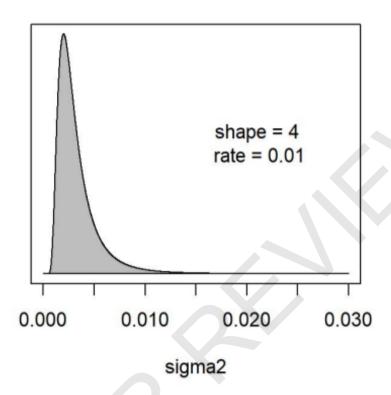


Figure 16: JABBA prior for process error for all model configurations.

Observation error

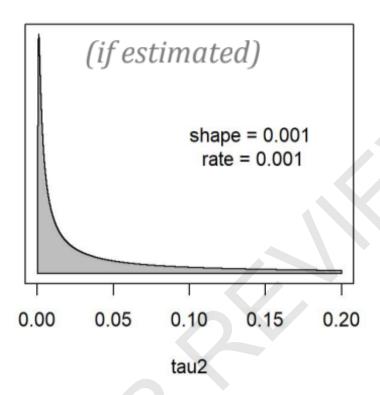


Figure 17: JABBA prior for observation error for all model configurations where estimated.

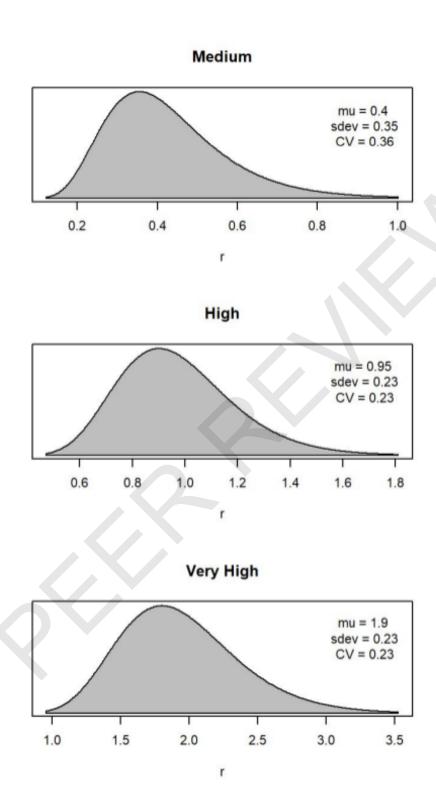
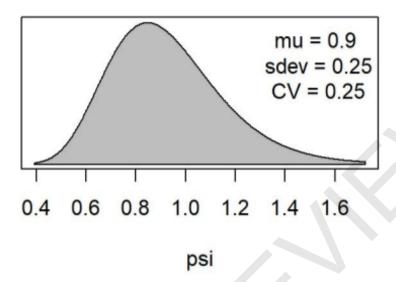


Figure 18: JABBA alternative prior assumptions for the intrinsic growth rate r.

Lower Initial Depletion



Higher Initial Depletion

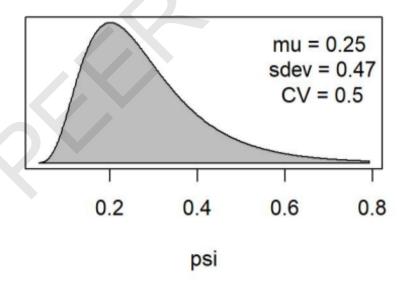


Figure 19: JABBA alternative prior assumptions for the initial biomass depletion ratio psi.

	Mod	Model Convergence Model Fit		Model Consistency			Process Error	Prediction Skill				
run	CONV_gw	CONV_hw	CONV_hs	CPUE_rt_rand	CPUE_rt_outl	RETRO_B	RETRO_F	RETRO_B.Bmsy	RETRO_F.Fmsy	ProcB_CI	HX_MASE	DIC
WSH_4_P_rM_psil0.9_sigT_60	FAIL	PASS	PASS	PASS	PASS	-0.05	0.09	-0.02	-0.03	PASS	1.17	-369.70
WSH_13_P_rH_psil0.9_sigF_60	FAIL	PASS	PASS	PASS	FAIL	-0.05	0.08	0.01	0.04	FAIL	1.13	-514.90
WSH_16_P_rM_psil0.9_sigF_60	PASS	PASS	PASS	PASS	FAIL	-0.00	0.01	0.04	-0.02	FAIL	1.12	-518.50
WSH_76_P_rM_psil0.2_sigT_60	PASS	PASS	PASS	PASS	PASS	0.01	0.00	0.21	-0.16	PASS	1.10	-462.50

Figure 20: Diagnostic tests for top performing JABBA models, where Run 16 was the "best model" that passed the most diagnostic tests.

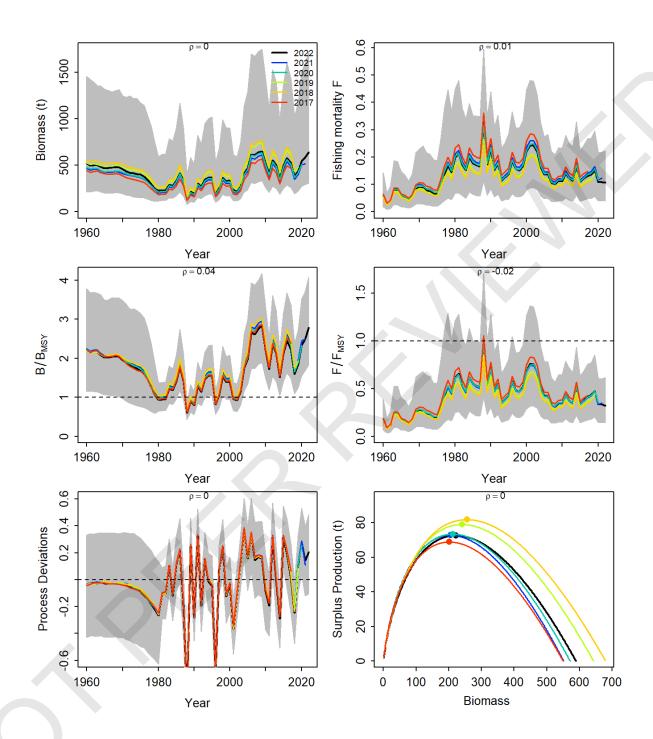


Figure 21: Retrospective analysis of key parameters and management quantities for top performing JABBA model run, with the line color corresponding to terminal years of data ranging from 2017:2022. Mohn's rho statistic (ρ) are denoted on top of the panels. Grey shaded areas are the 95% credible intervals from the reference model. Biomass and surplus production are reported in million lb tail weight.

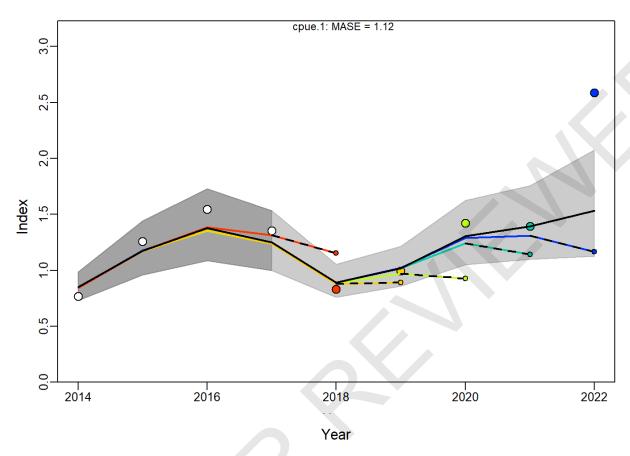


Figure 22: Hindcasting cross-validation (HCxval) results from CPUE fits, showing observed (large points), fitted (solid lines) and one-year ahead forecast values (small terminal points). HCxval was performed using one reference model (black line) and five hindcast model runs (colored lines with terminal years 2018 to 2022) relative to the expected CPUE. The mean absolute scaled error (MASE) score scales the mean absolute error (MAE) of forecasts (i.e., prediction residuals) to MAE of a naïve in-sample prediction (CPUE value this year = CPUE value from last year).

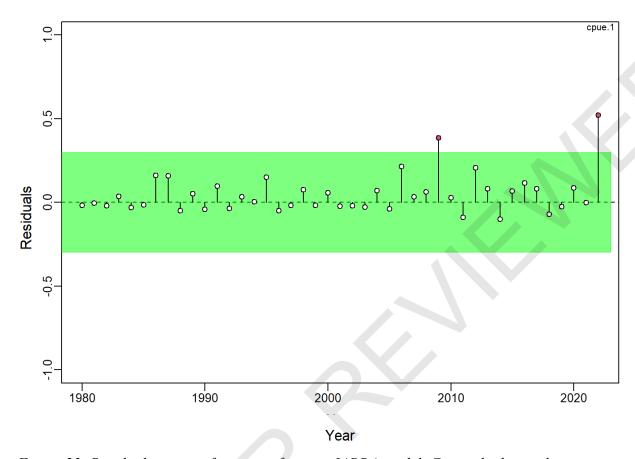


Figure 23: Residual runs test for top performing JABBA model. Green shading indicates no evidence (p=0.05) and red shading evidence (p<0.05) to reject the hypothesis of a randomly distributed time-series of residuals, respectively. The shaded (green/red) area spans three residual standard deviations to either side from zero, and the red points outside of the shading violate the 'three-sigma limit' for that series.

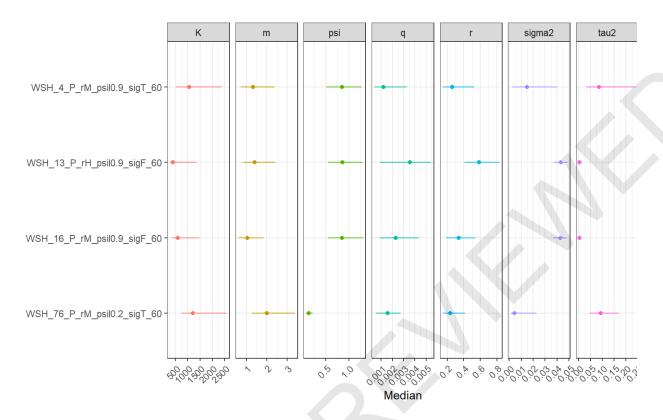


Figure 24: Parameter estimates and error for top performing JABBA models.

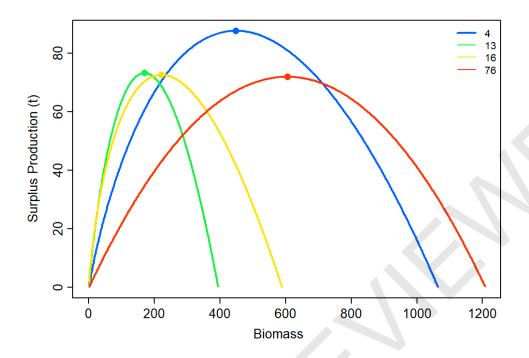


Figure 25: Surplus production and associated biomass estimated for all top performing models (in million lb tail weight).

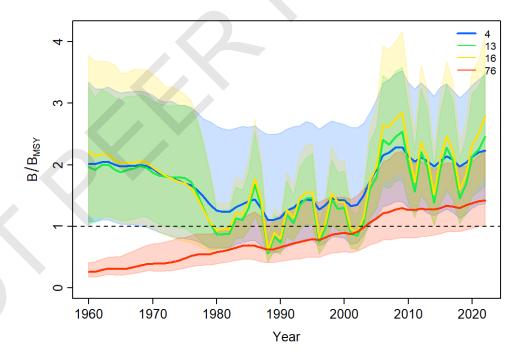


Figure 26: B/Bmsy trajectories for top performing JABBA models, where Run 16 (yellow) was the "best model" but did not pass diagnostic tests. Runs 4 and 13 (green and blue) did not converge.

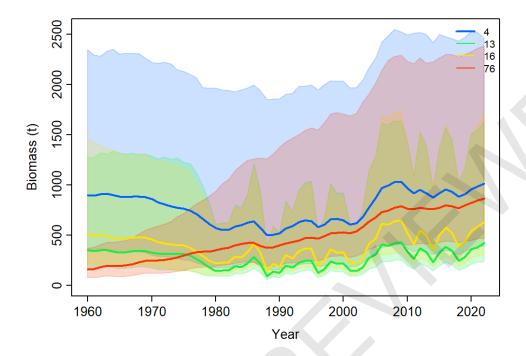


Figure 27: Biomass trajectories (in million lb tail weight) for top performing JABBA models, where Run 16 (yellow) was the "best model" but did not pass diagnostic tests.

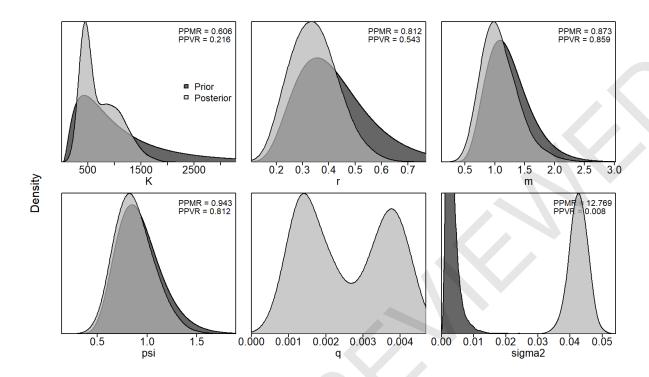


Figure 28: Posteriors for top JABBA model (did not pass diagnostic tests).

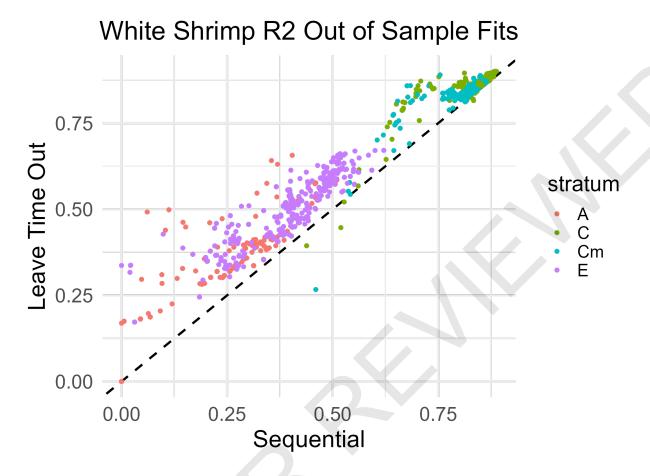


Figure 29: Out-of-sample R2 statistics for each model configuration using the 'leave time out' vs. the 'sequential' cross validation approach. While 'leave-time-out' obtains better model fits, the purpose here is to be able to project well into the future, which is better captured by the 'sequential' approach. Models are filtered based on the R2 statistics from the 'sequential' prediction method going forward.

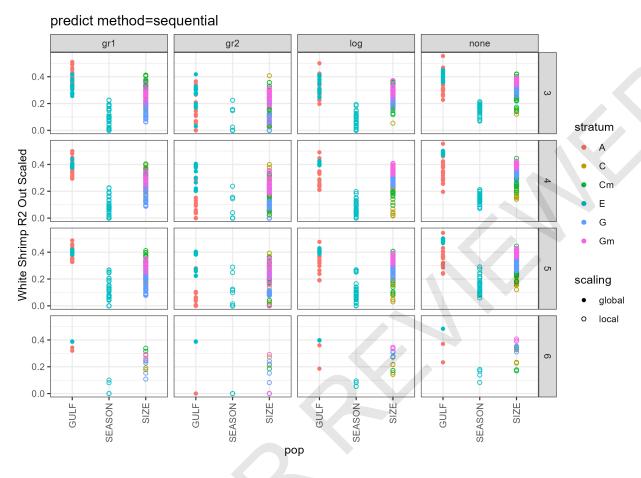


Figure 30: "Sequential" out-of-sample R2 fit statistic resulting from each model run. Facet columns show results based on different data transformations. Facet rows show results based on the embedding dimension. Within each facet, the x axis groups the models by the type of aggregation (spatial, size, season, or a combination).

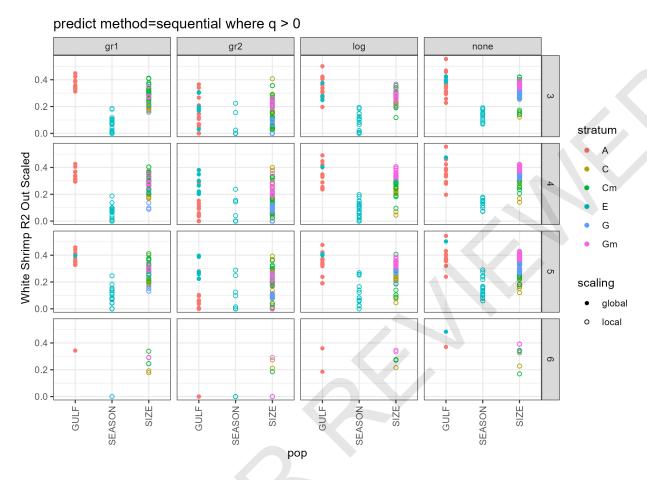


Figure 31: "Sequential" out-of-sample R2 fit statistic resulting from each model run with "local" scaling. Facet columns show results based on different data transformations. Facet rows show results based on the embedding dimension. Within each facet, the x axis groups the models by the type of aggregation (spatial, size, season, or a combination). Models that fit to the survey data and ignored landings (e.g. q=0) were removed from further consideration.

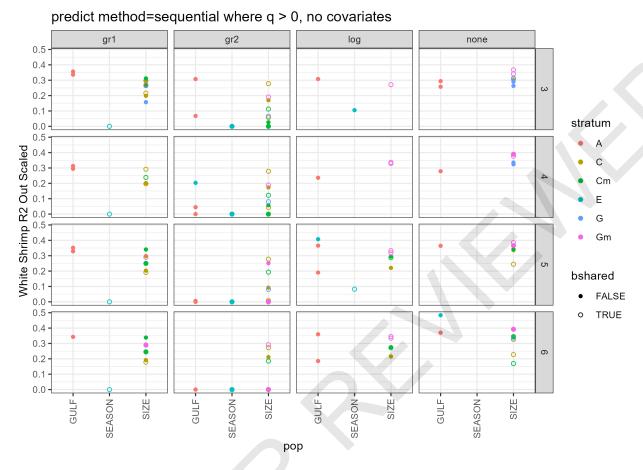


Figure 32: "Sequential" out-of-sample R2 fit statistic resulting from each model run with "local" scaling, q > 0.001, and no covariates. Facet columns show results based on different data transformations. Facet rows show results based on the embedding dimension. Within each facet, the x axis groups the models by the type of aggregation (spatial, size, season, or a combination). In this figure, the shape fill was determined by whether or not the catchability parameter was shared among populations in the model (bshared = True / False, respectively).

WSH_C4182 Large Projections

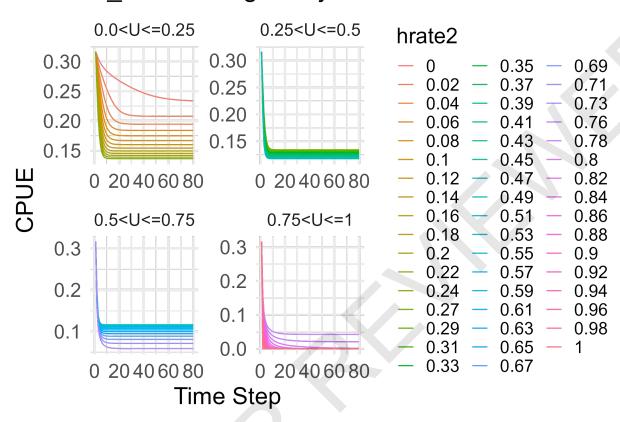


Figure 33: Variable harvest rate projections of CPUE from the best performing run for the Large shrimp population.

WSH_C4182 Medium Projections

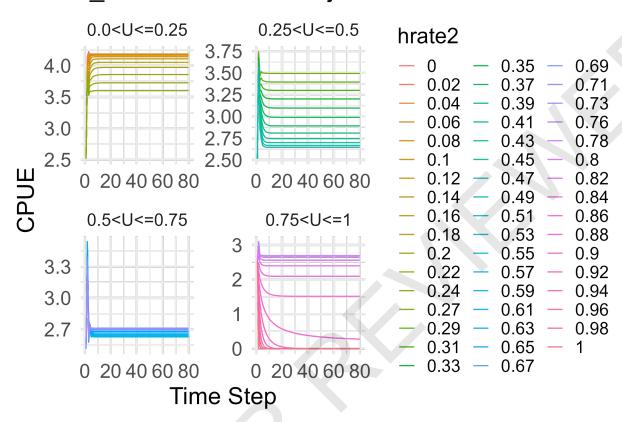


Figure 34: Variable harvest rate projections of CPUE from the best performing run for the Medium shrimp population.

WSH_C4182 Small Projections

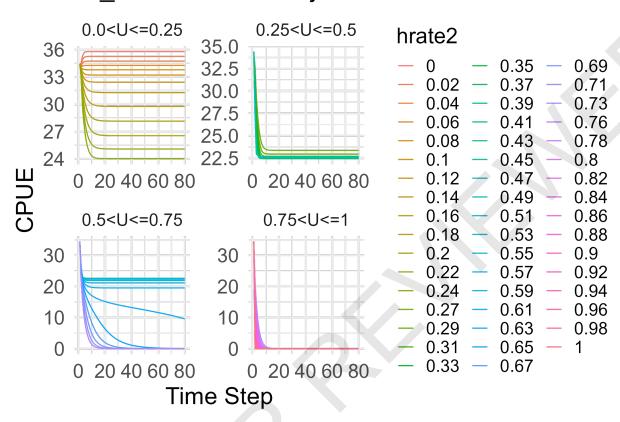


Figure 35: Variable harvest rate projections of CPUE from the best performing run for the Small shrimp population.

WSH_C4182 Large Projections

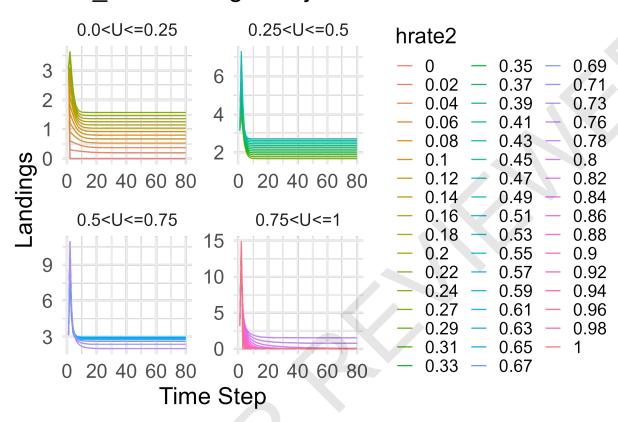


Figure 36: Variable harvest rate projections of landings from the best performing run for the Large shrimp population.

WSH_C4182 Medium Projections

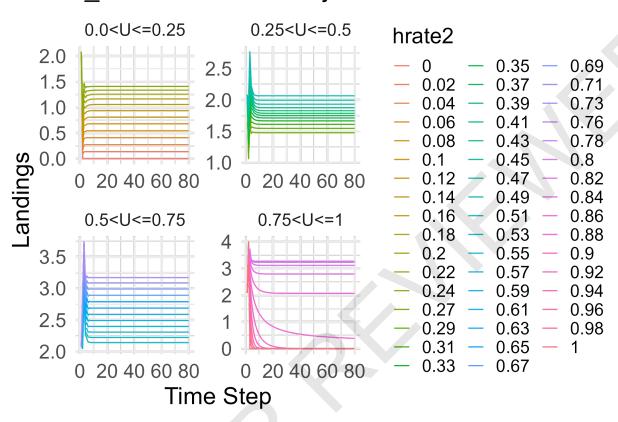


Figure 37: Variable harvest rate projections of landings from the best performing run for the Medium shrimp population.

WSH_C4182 Small Projections

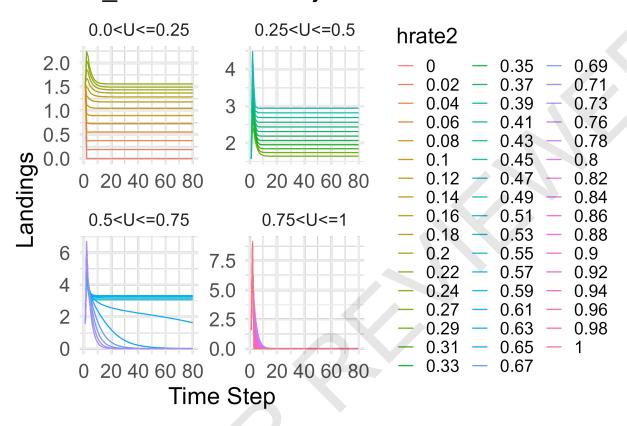


Figure 38: Variable harvest rate projections of landings from the best performing run for the Small shrimp population.

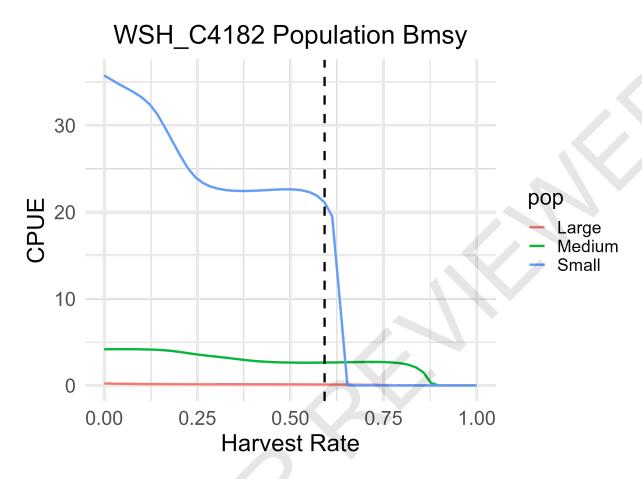


Figure 39: Average CPUE by harvest rate for individual populations for the best performing run. The dashed line indicates the annual harvest rate where MSY occurs, indicating population-wide Bmsy in units of CPUE for each population.

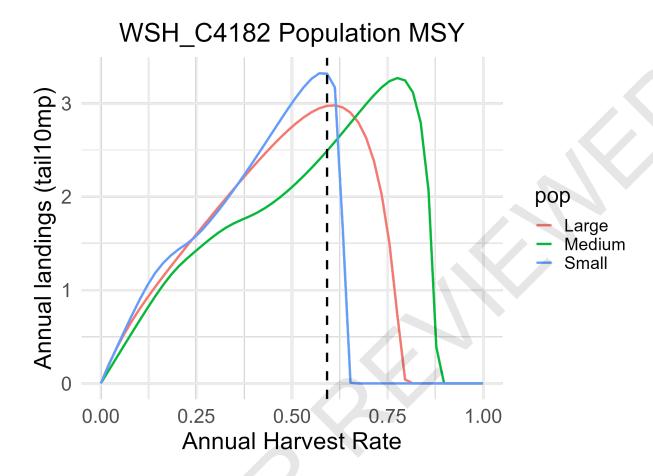


Figure 40: Average landings estimated under a range of annual harvest rates for the best performing run. The optimal annual harvest rate for all populations combined is shown in the dashed line. Individual populations see their landings maximized at slightly different harvest rates.

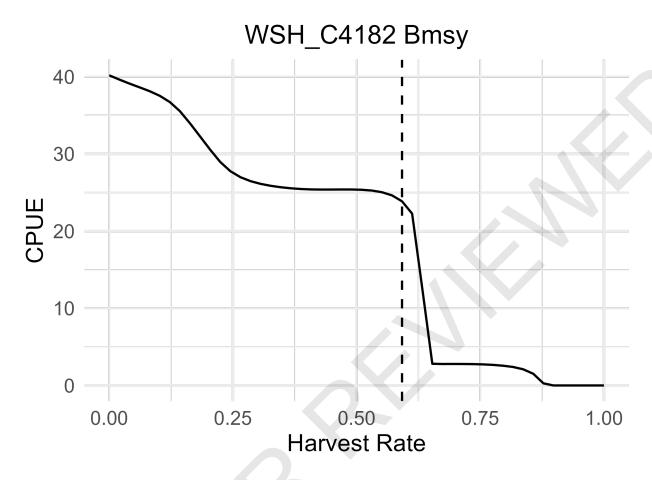


Figure 41: Average CPUE for all populations combined for the best performing run. The dashed line indicates the annual harvest rate where MSY occurs, indicating population-wide Bmsy in units of CPUE.

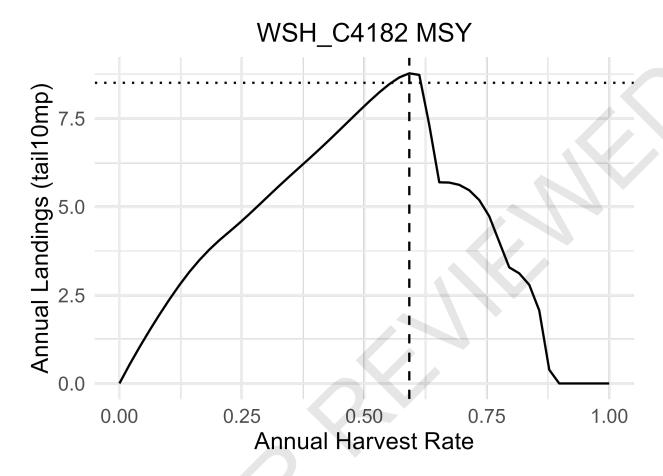


Figure 42: Average landings estimated under a range of annual harvest rates for the best performing run. The optimal annual harvest rate for all populations combined (MSY) is marked with a vertical dashed line. The maximum historical landings are marked with a horizontal dotted line, which is less than the estimated MSY.

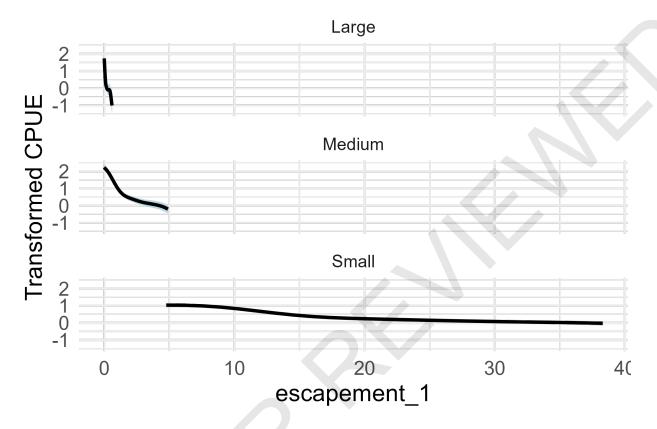


Figure 43: Length scale parameters for the 1st lag of abundance from the best performing model.

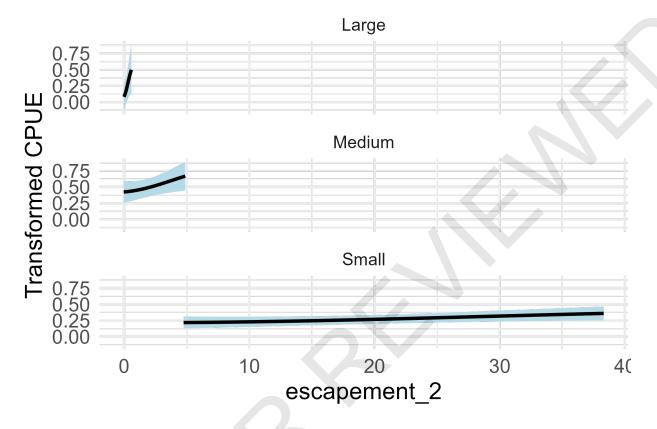


Figure 44: Length scale parameters for the 2nd lag of abundance from the best performing model.

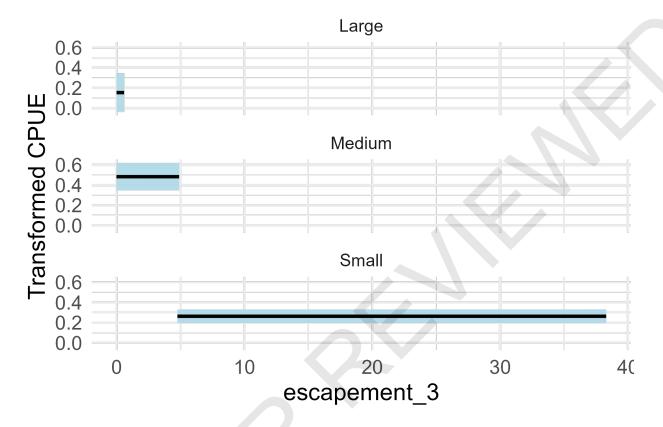


Figure 45: Length scale parameters for the 3rd lag of abundance from the best performing model.

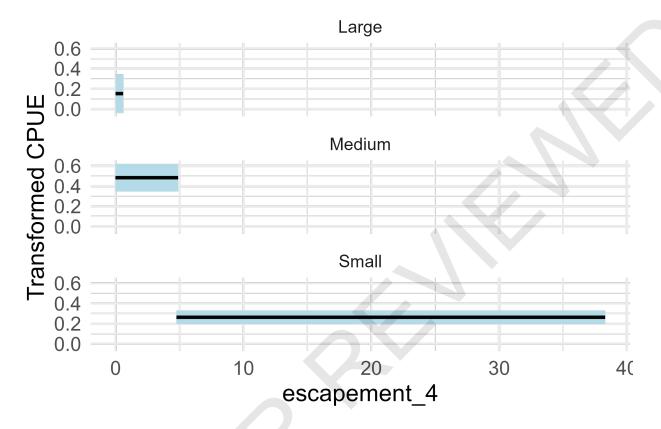


Figure 46: Length scale parameters for the 4th lag of abundance from the best performing model.

White Shrimp Abundance

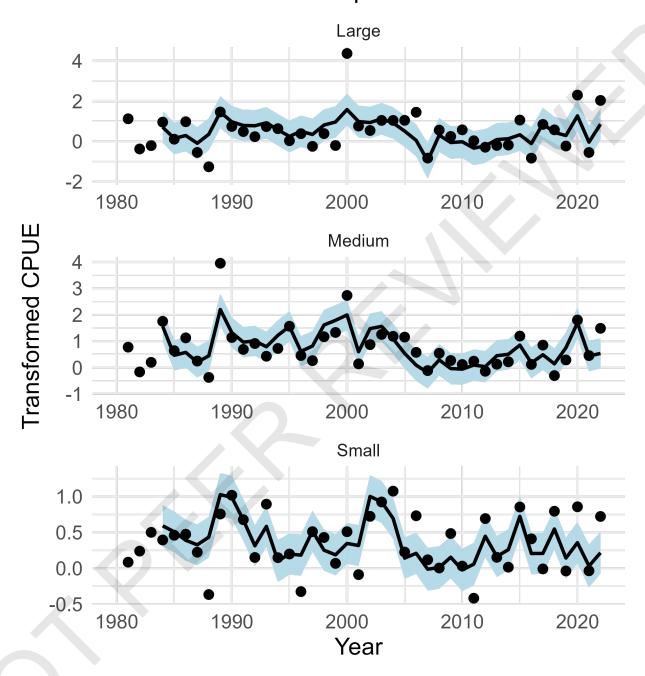


Figure 47: EDM model fits for the best performing run, transformed with error bars.

White Shrimp Abundance

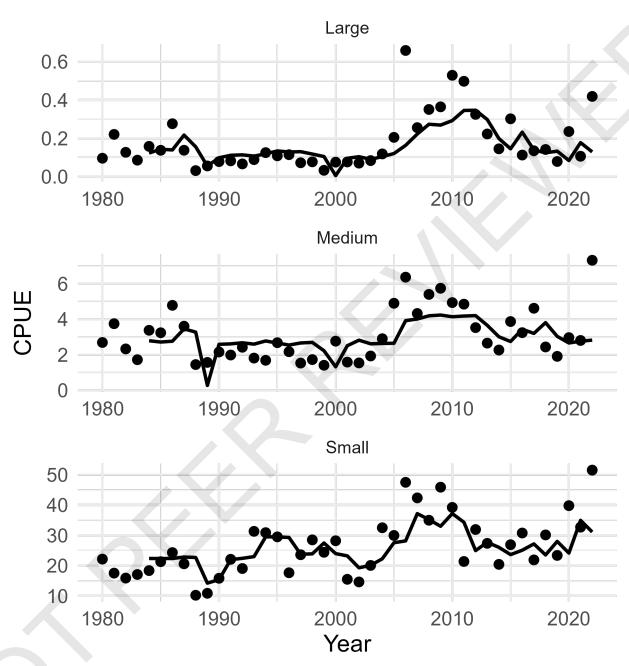


Figure 48: EDM model fits for the best performing run in raw units of LDWF CPUE.